

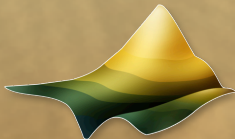
Earth Science Lidar Topography Applications

Chris Crosby

San Diego Supercomputer Center @ UCSD

Featuring work from colleagues:

J Ramón Arrowsmith (ASU); David Phillips (UNAVCO); Mike Oskin (UC Davis),
Kurt Frankel (GA Tech)



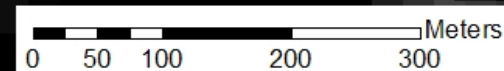
Introduction:

- Landscape development a combination of many processes:
 - Tectonic
 - Hillslope
 - Fluvial
 - Biologic
 - Anthropogenic
- High-resolution representation of landscape is central to qualitative and quantitative study of process.
- Aerial photography traditional tool for geomorphic studies
- 2D representation
- Qualitative tool



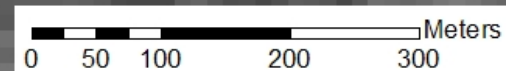
Introduction:

- Digital topography provides 2.5D representation of landscape
- Widely avail. digital topography (digital elevation models - DEMs) are too coarse to provide representation of small geomorphic features / process.
- USGS 30 m DEM = best available national coverage



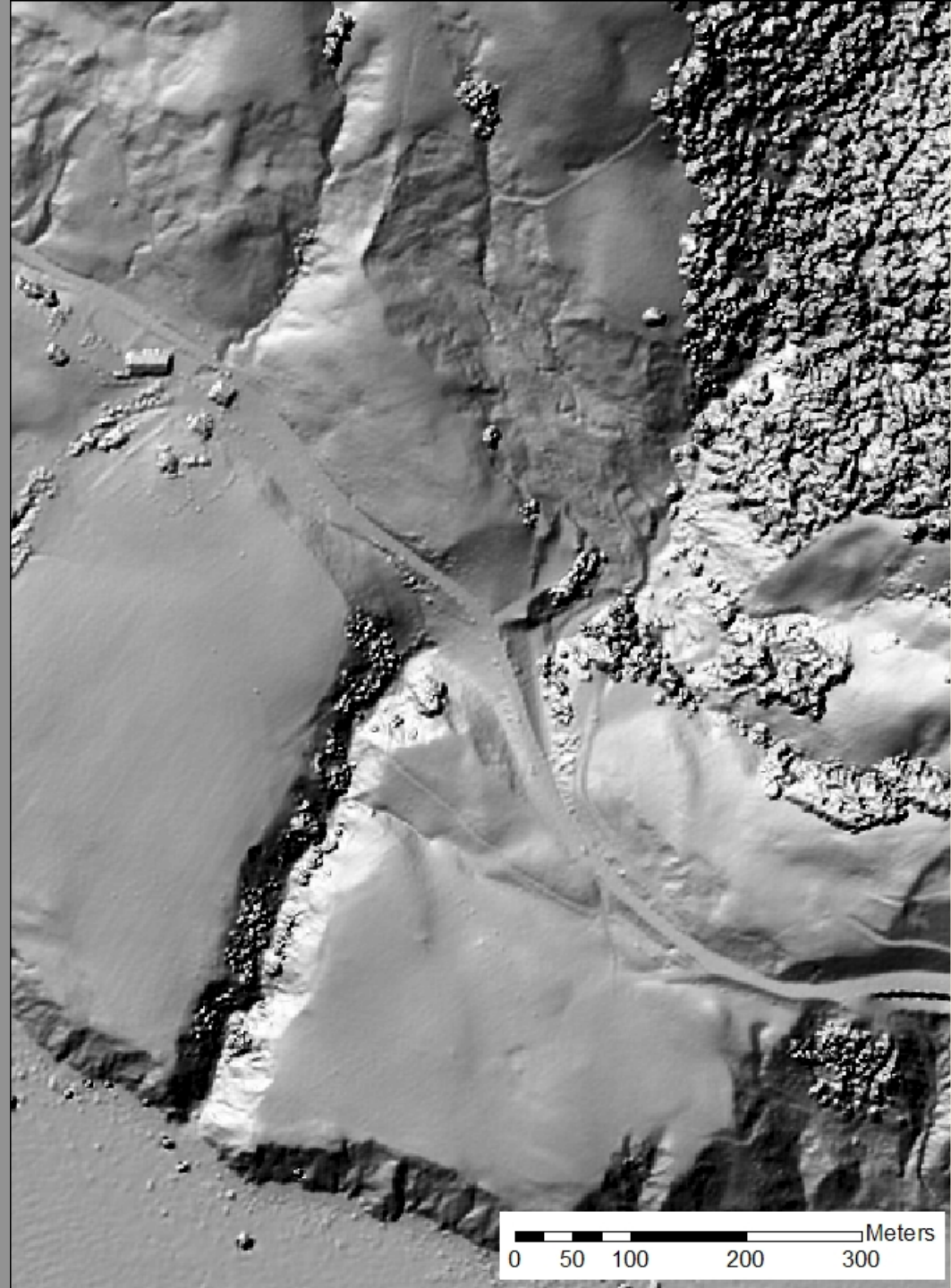
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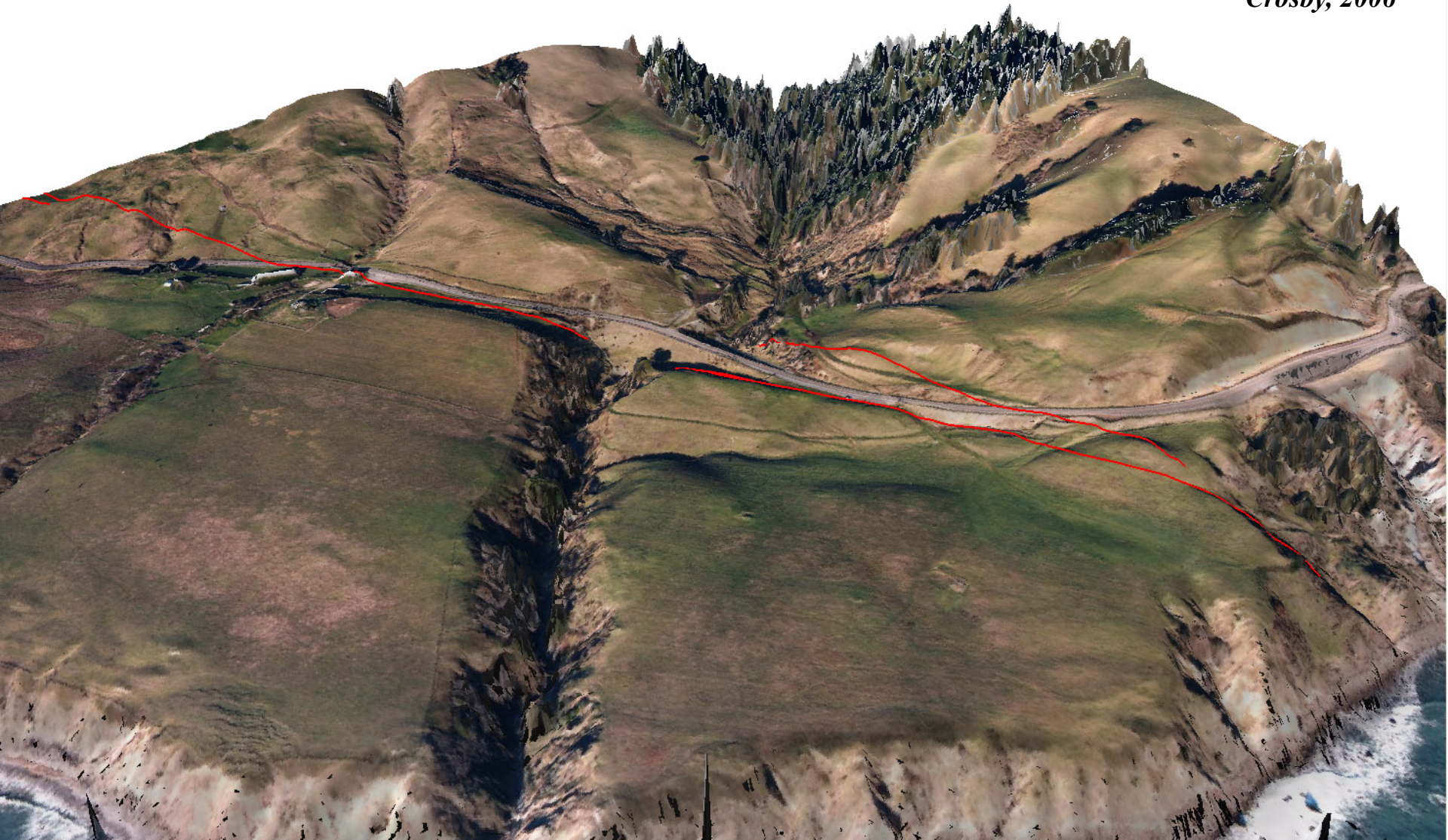
Introduction:

- LiDAR / ALSM data
- DEMs at resolutions not previously possible.
 - sub-meter resolution
 - Measure features at the appropriate scale
- Applicable to:
 - Geomorphology
 - Landslide & flood hazards
 - Forestry/Ecology
 - Civil Engineering
 - Urban planning
 - Volcanology
- One of the hottest tools in the Geosciences



3D visualization: DEM + air photo fusion

Crosby, 2006

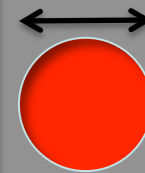


Airborne Lidar 101

lidar = **l**ight **d**etection **a**nd **r**anging (*aka* airborne laser swath mapping)



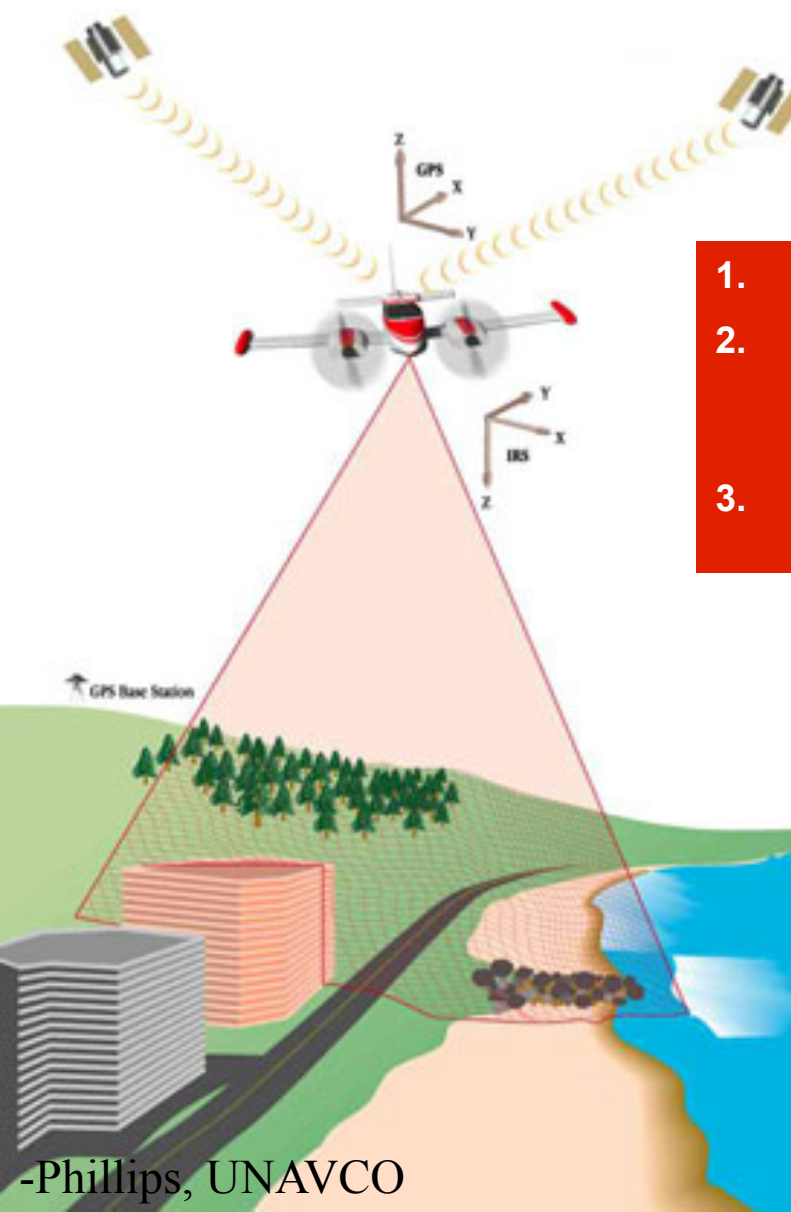
- collected at 10s to 100s of kHz
- Vertical accuracy ~ 15 cm



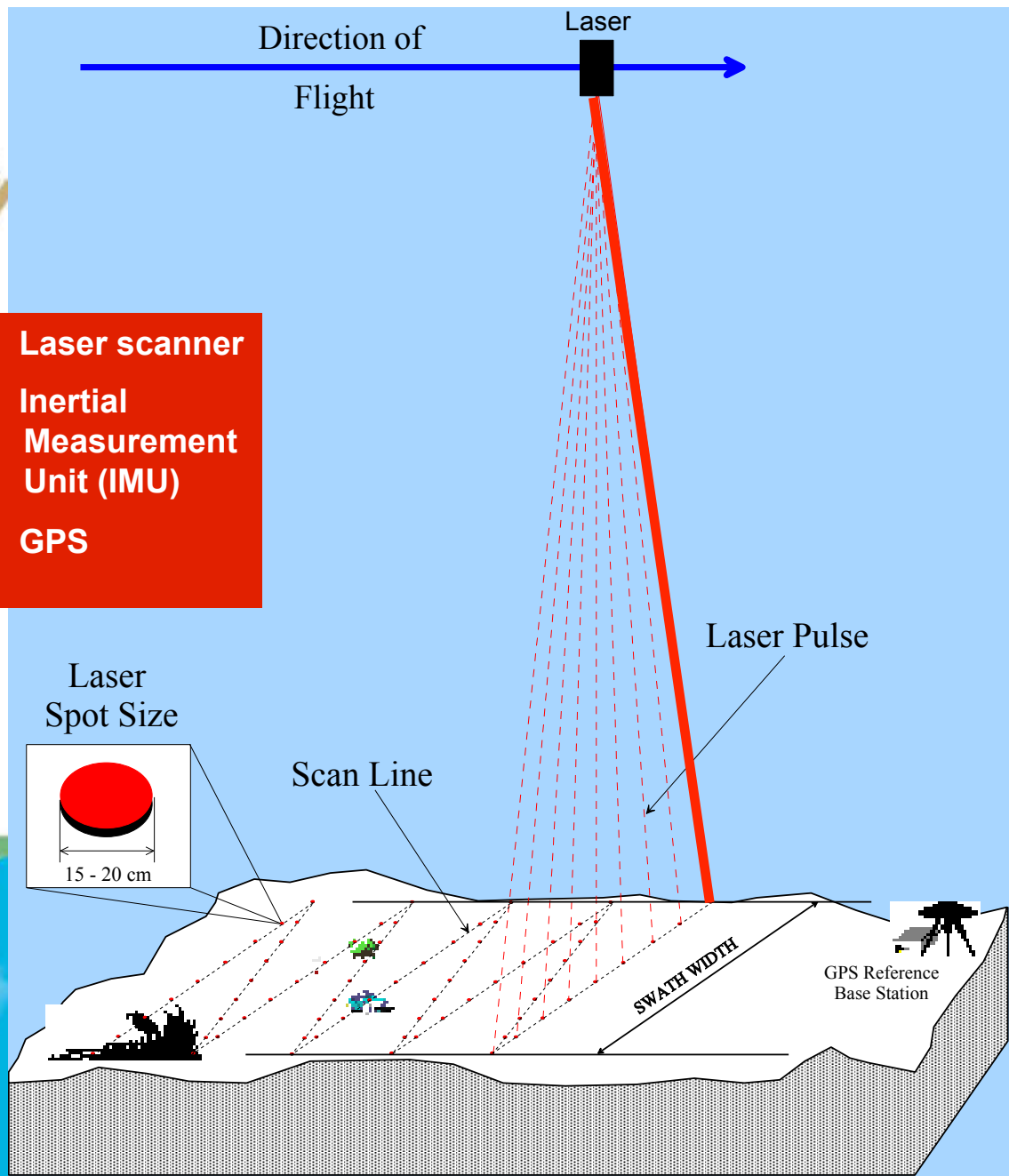
- Beam diameter 15-20 cm

- 10^6 to 10^9 measurements of ground, vegetation, structures
 - *Point cloud* (x, y, z coordinates) = fundamental lidar data product
- Earth's surface > 8 times per meter²

Airborne Laser Swath Mapping (ALSM)

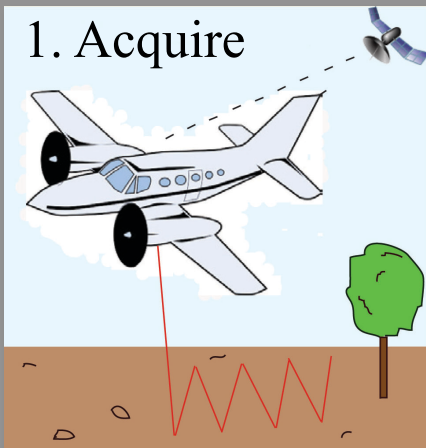


1. Laser scanner
2. Inertial Measurement Unit (IMU)
3. GPS



Airborne Lidar Workflow

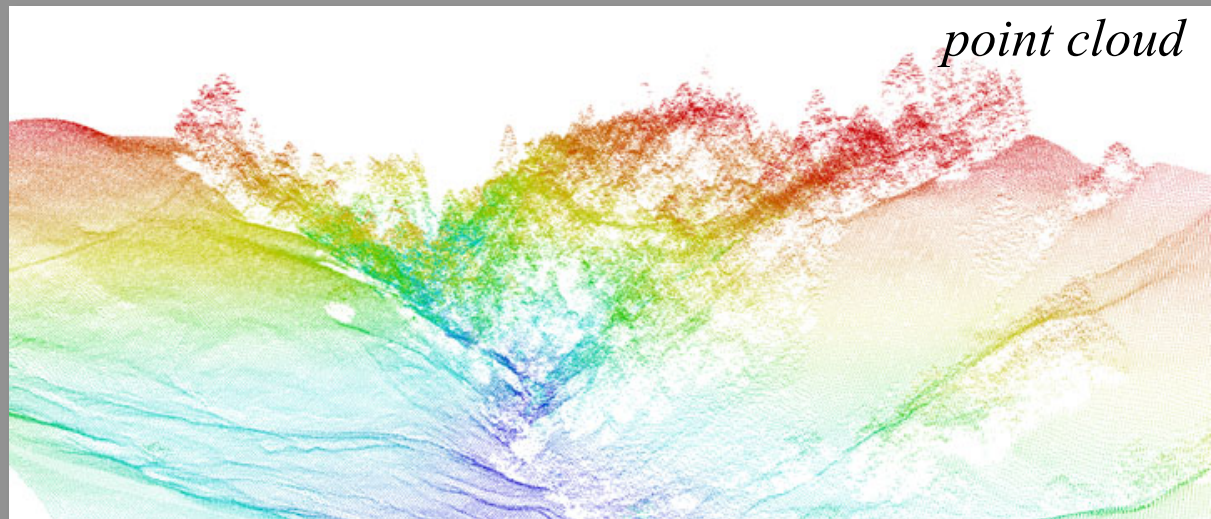
1. Acquire



2. Process

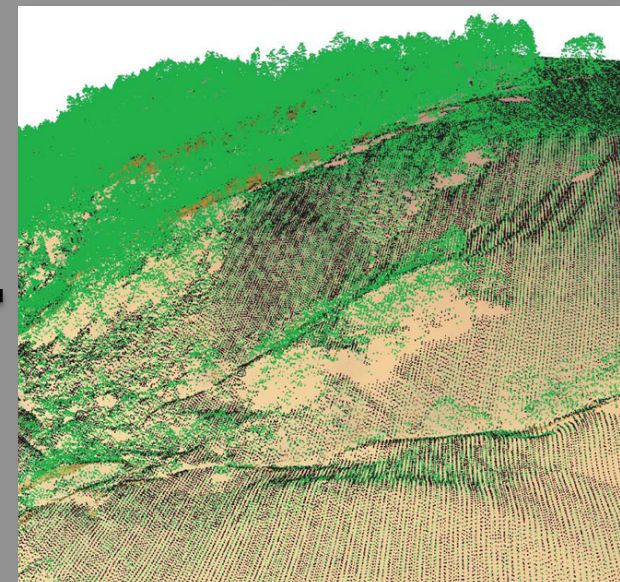


Laser
+ *GPS*
+ *IMU*



point cloud

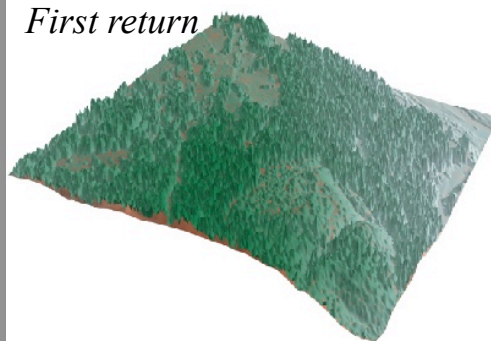
3. Classify
(filter)



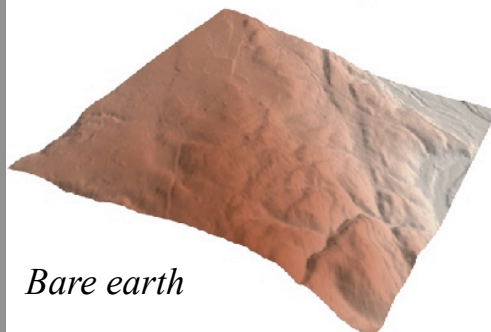
4. Grid



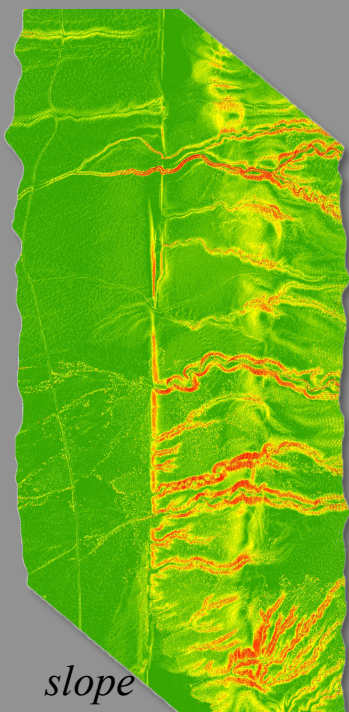
First return



Bare earth

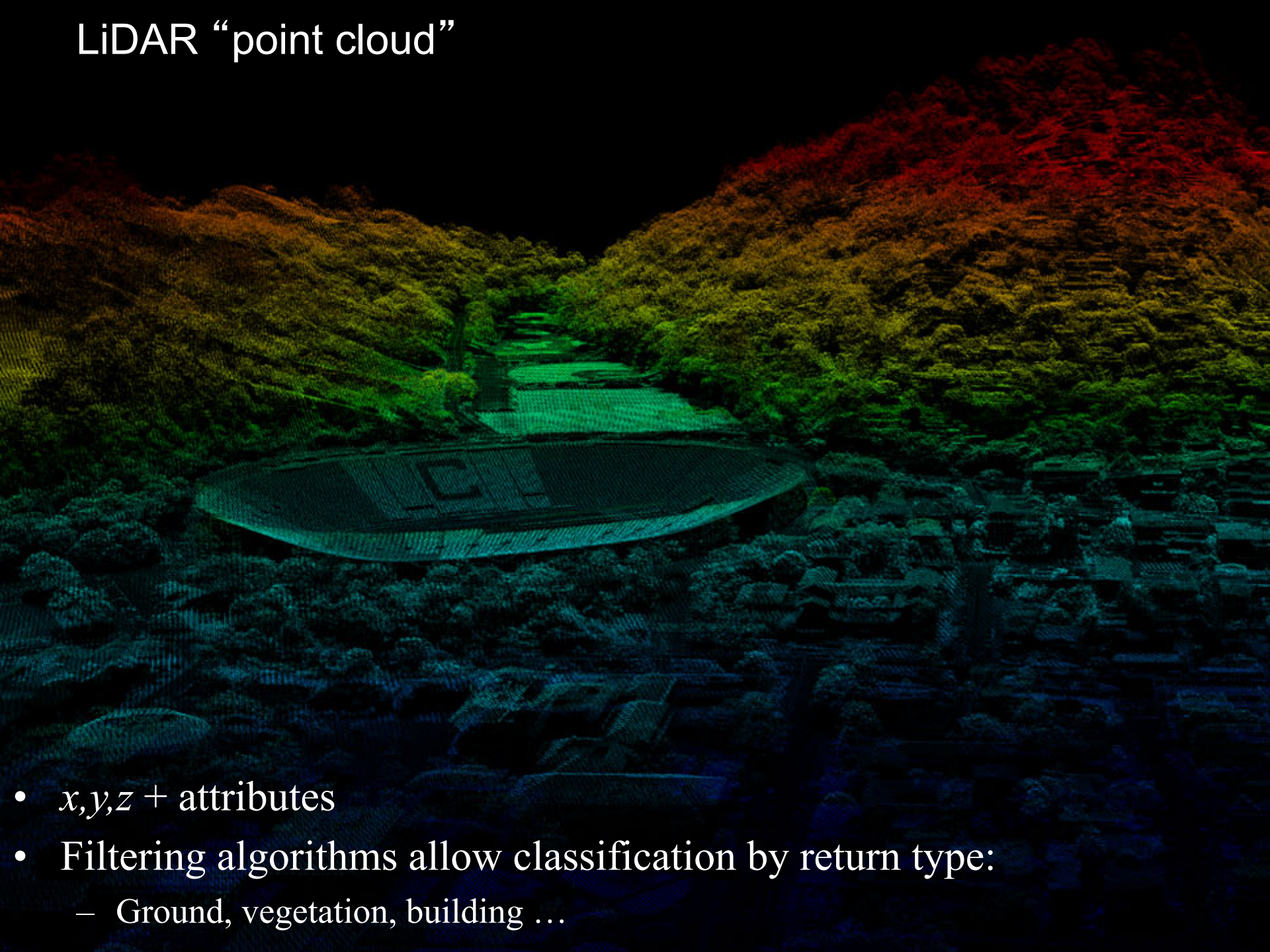


5. Generate
Derivatives



slope

LiDAR “point cloud”



- x, y, z + attributes
- Filtering algorithms allow classification by return type:
 - Ground, vegetation, building ...

Comparisons of Techniques for measuring surfaces and detecting changes in surfaces*

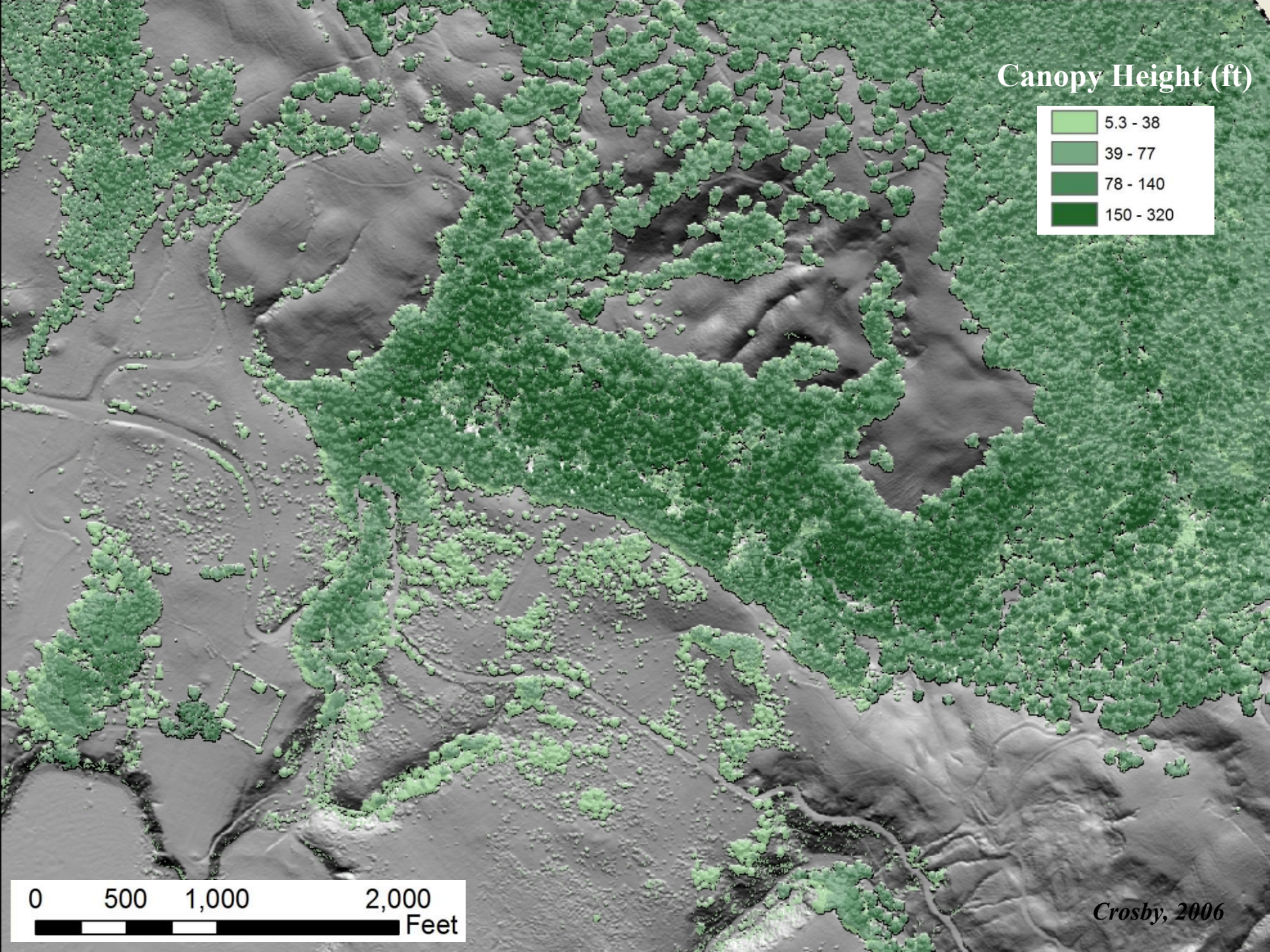
	GPS	InSAR	ALSM	TLS
Sample Density	1 site/10 km ²	10,000 pixels/ km ²	1- >14 hits/ m ²	1000 hits/ m ²
Position Precision	1-20 mm	2-3 m	5-15 cm	0.6-5 cm
Change Detection	1 mm	1-2 cm	10 cm	1 cm
Scale	Global	100 km	10-100 Km	1 km

* Ball park numbers for typical applications

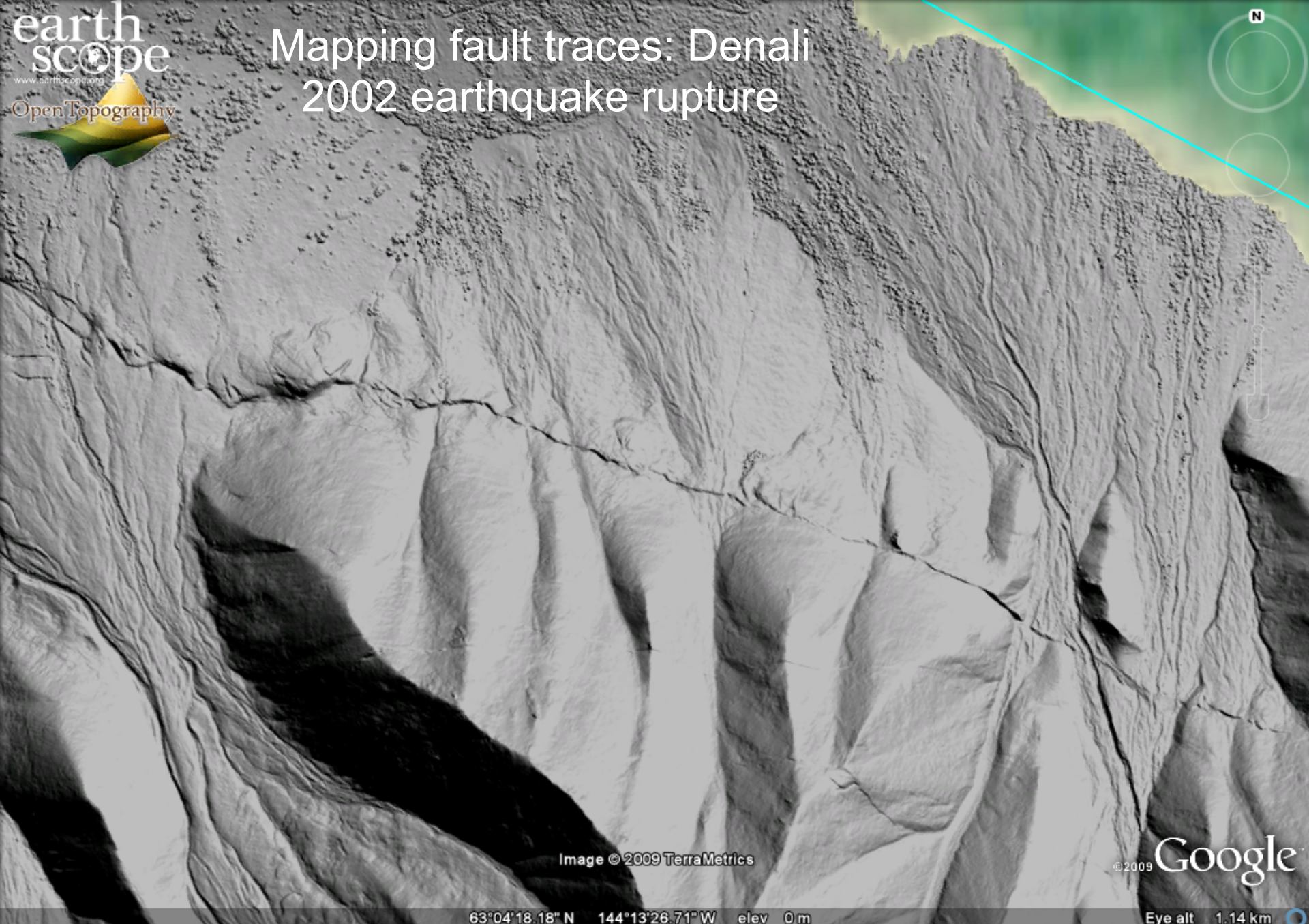
-Phillips, Meertens, and Jackson, UNAVCO







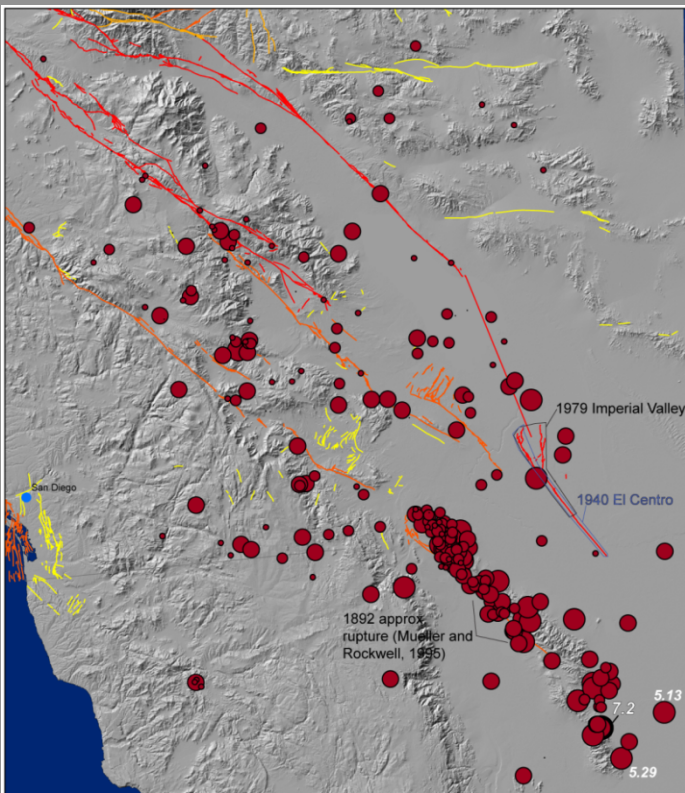
Mapping fault traces: Denali 2002 earthquake rupture



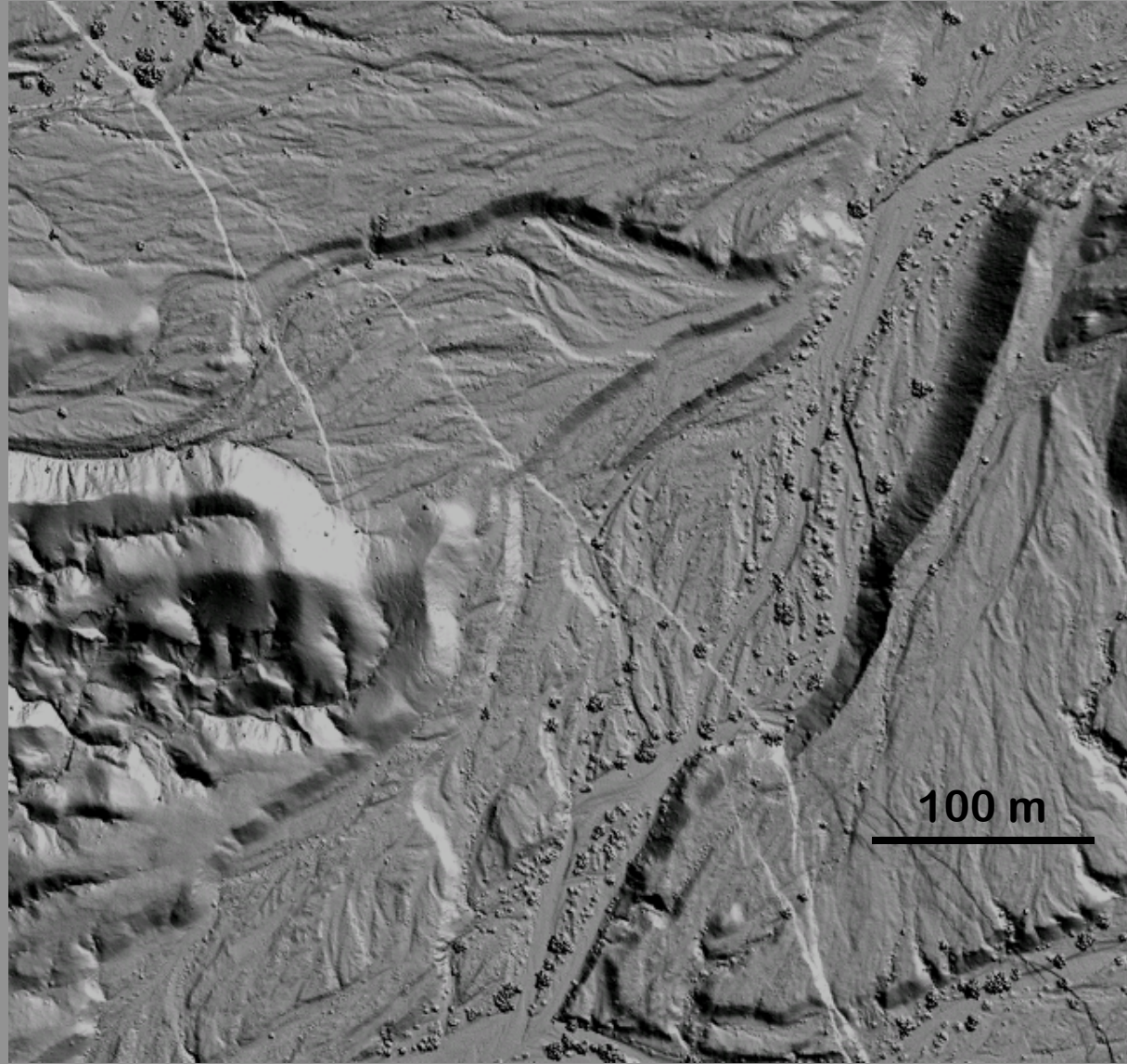
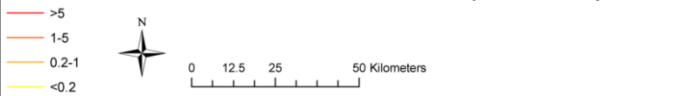
Post earthquake laser scanning and repetition (B4, Hector Mine, Denali)

Post El Mayor-Cucupah EQ Scan

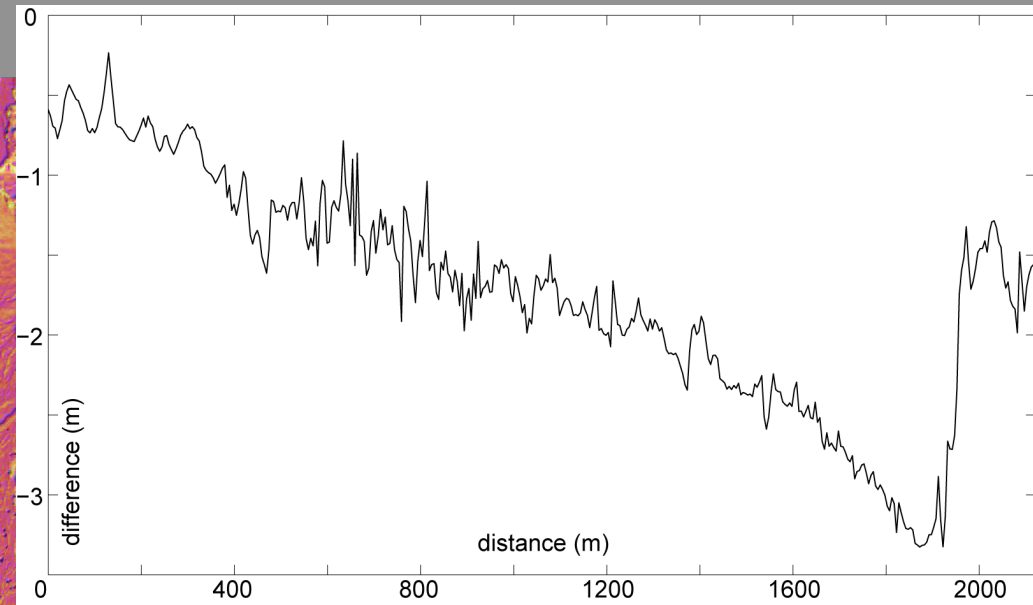
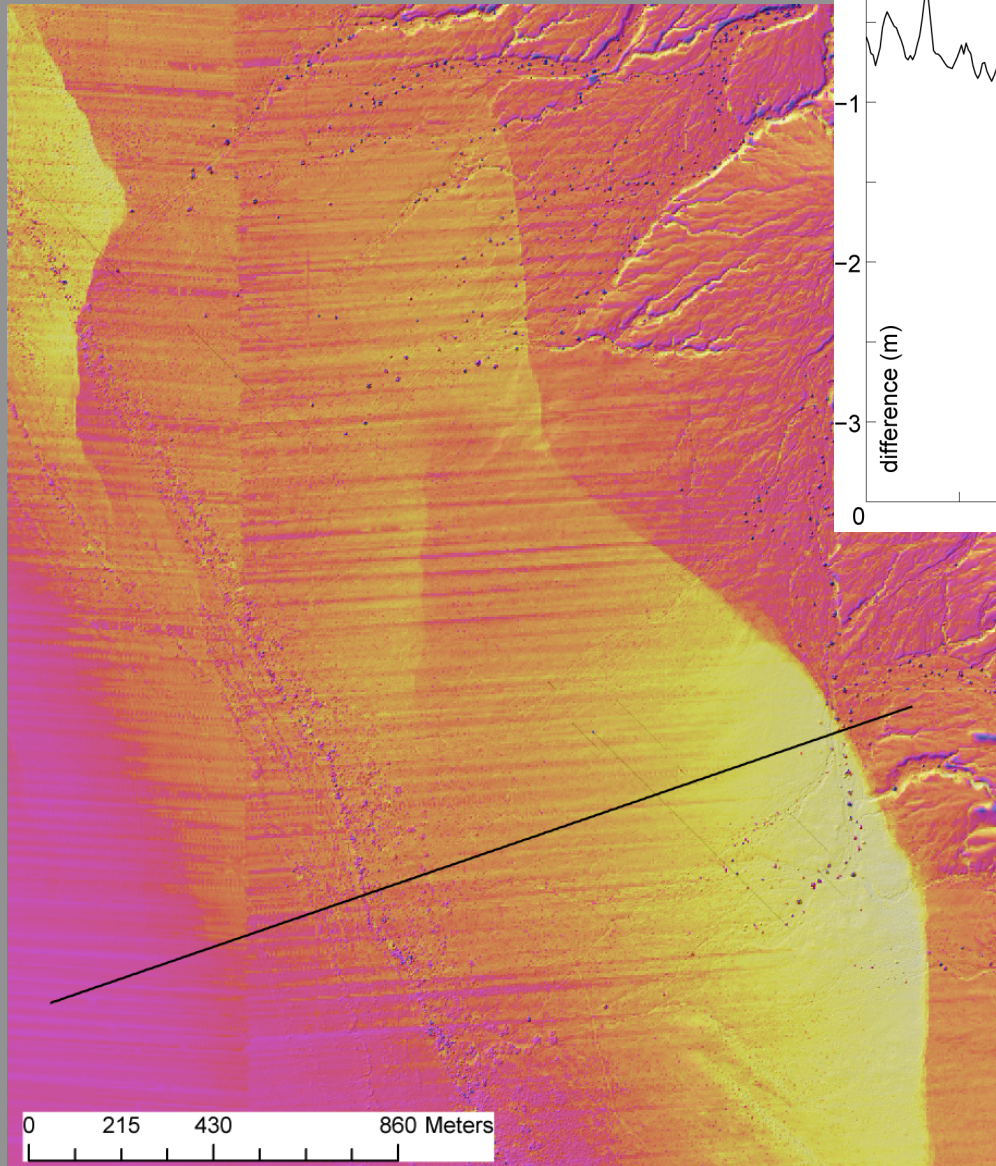
- Oskin, Arrowsmith, Hinojosa, Fletcher (NSF Rapid + SCEC); collected by NCALM



Fault slip rate (mm/yr) Main shock and ~12 hours seismicity/aftershocks Baja California



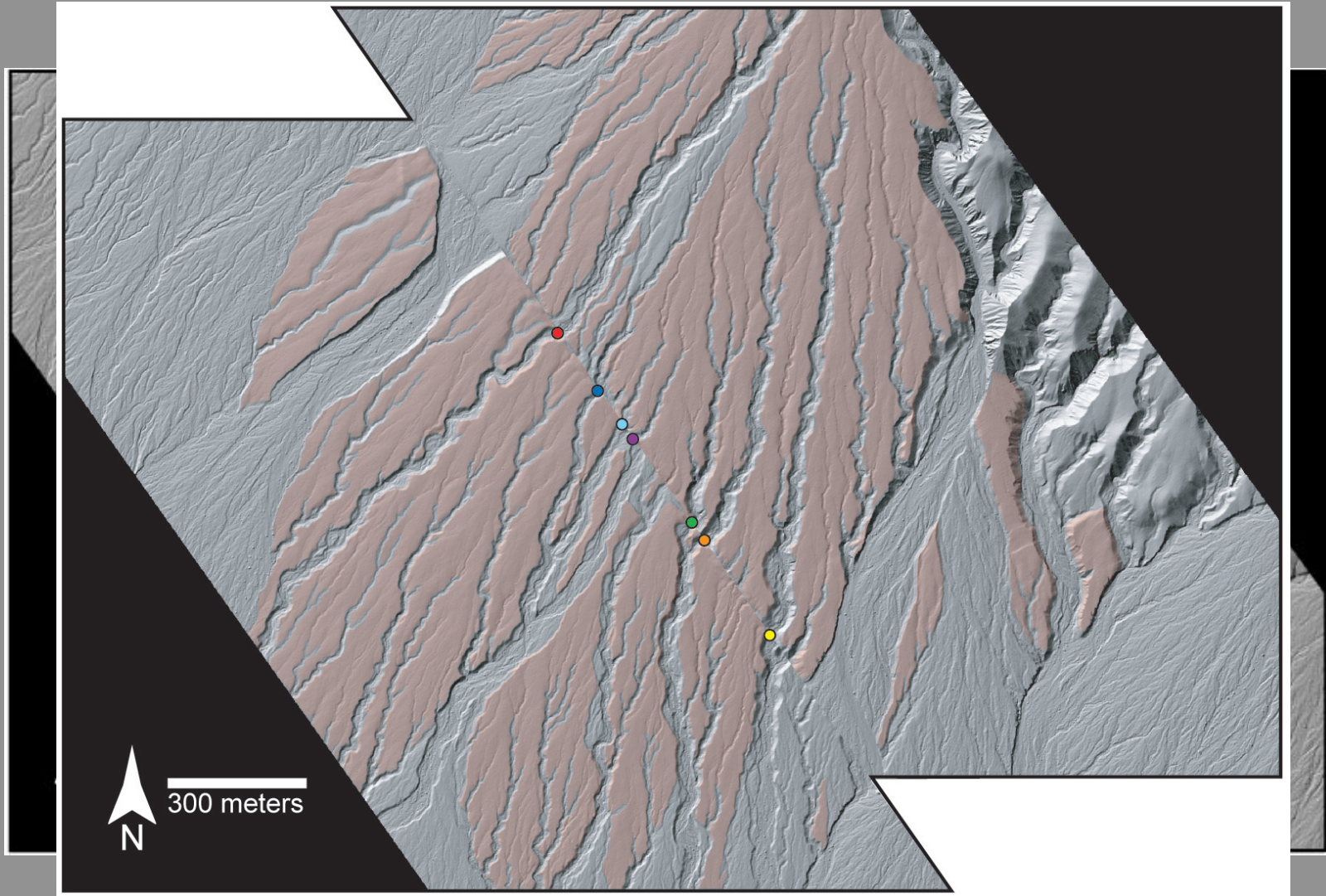
Change Detection with LiDAR Data



- vertical different pre- and post-El Mayor- Cucupah earthquake
- subtract 5 m pre-earthquake INGEI DEM from 5 m post-earthquake DEM

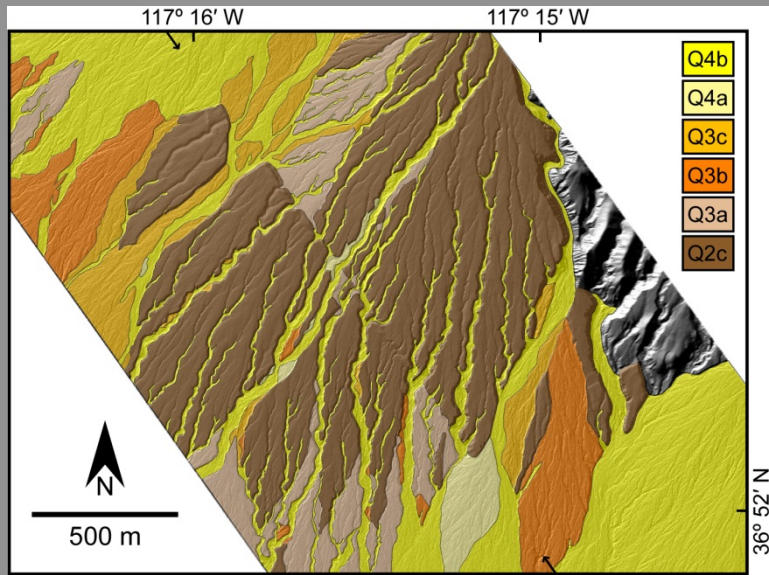
Arrowsmith, Oskin, Fletcher, Hudnut, in submitted

Red Wall Canyon Offset

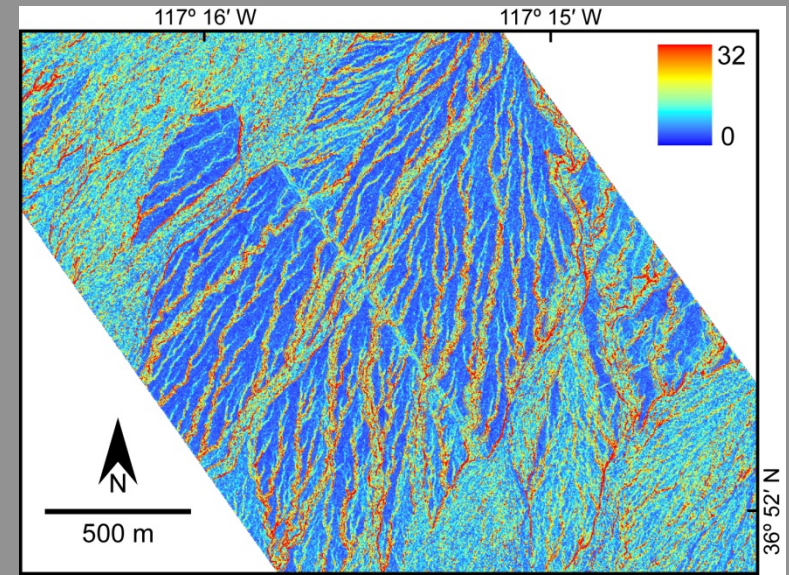


- total displacement = 297 ± 9 meters

Objective Mapping with Roughness

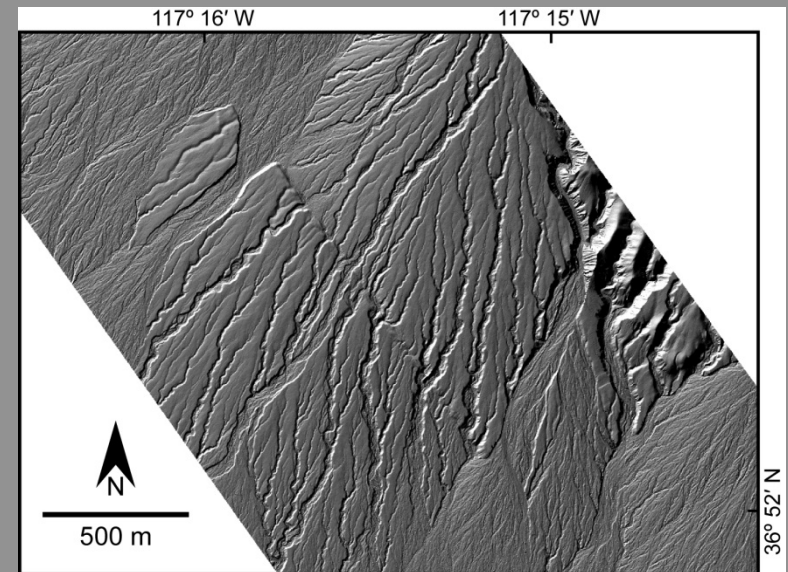


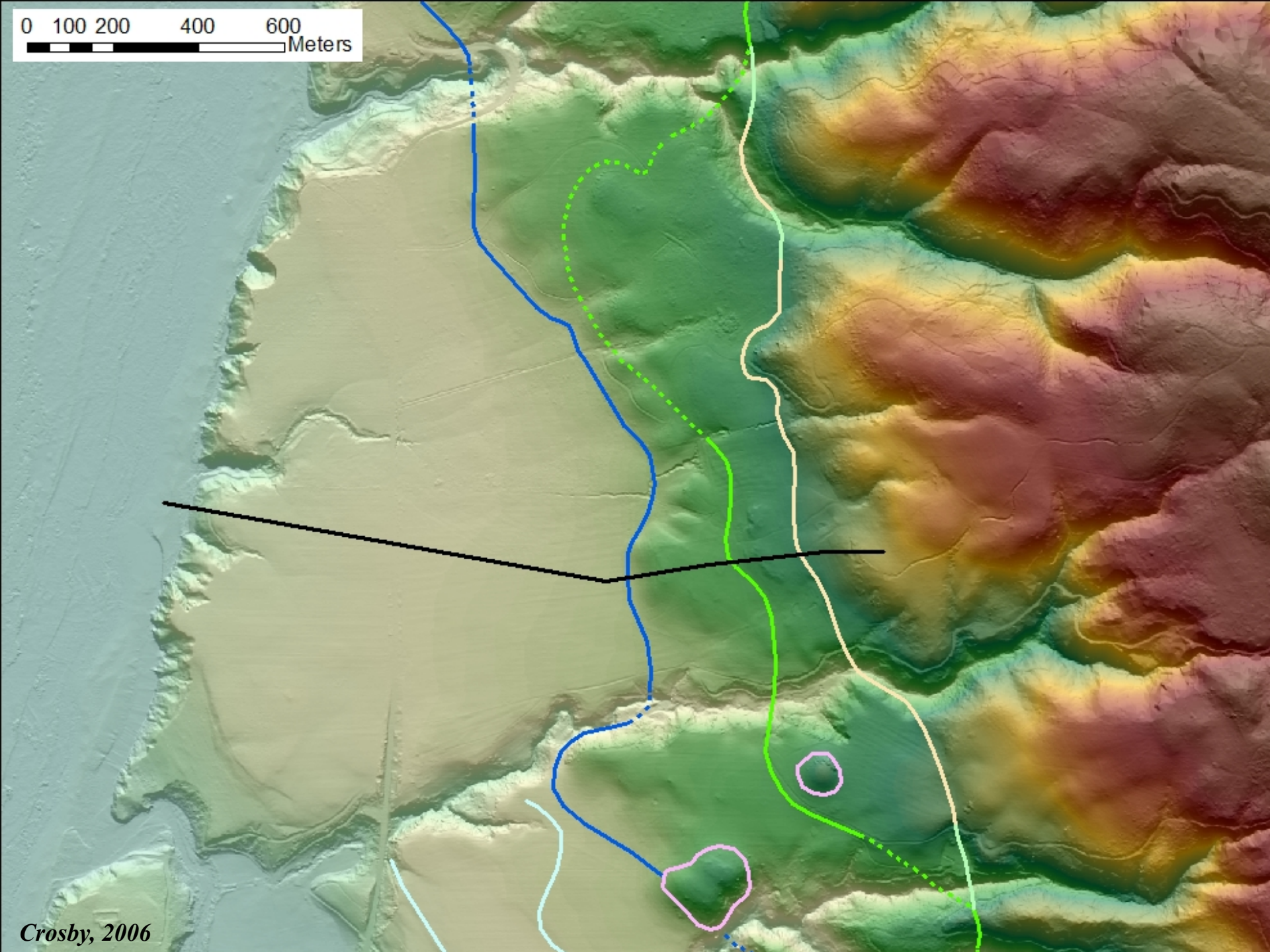
- surficial geologic map

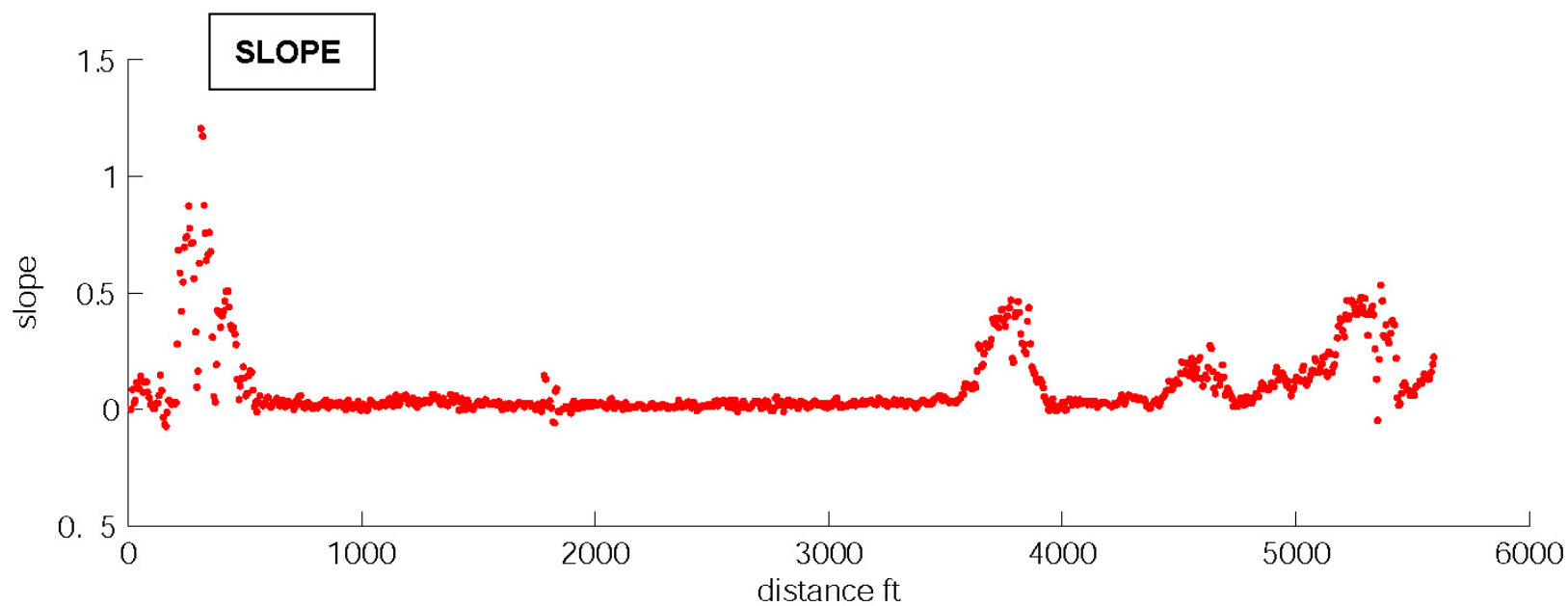
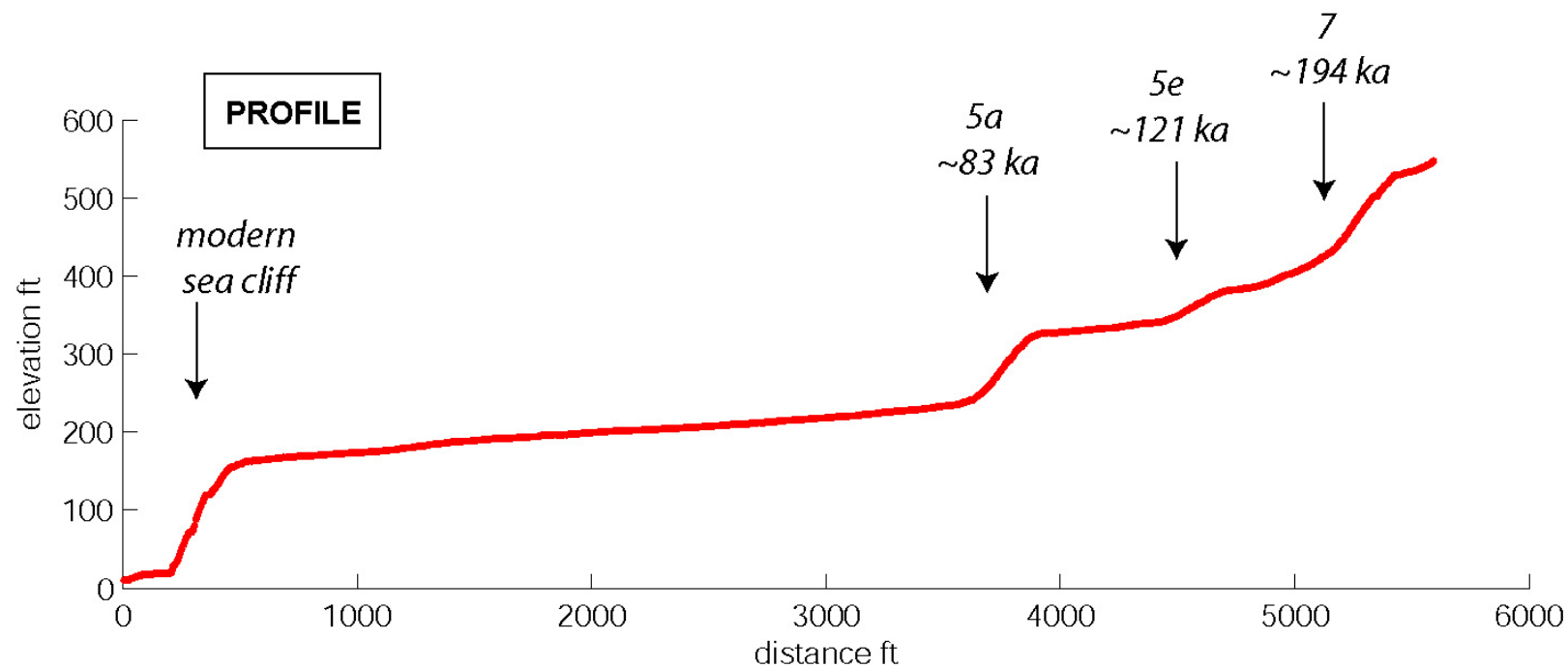


- surface roughness map

- bare-earth DEM (1 m)

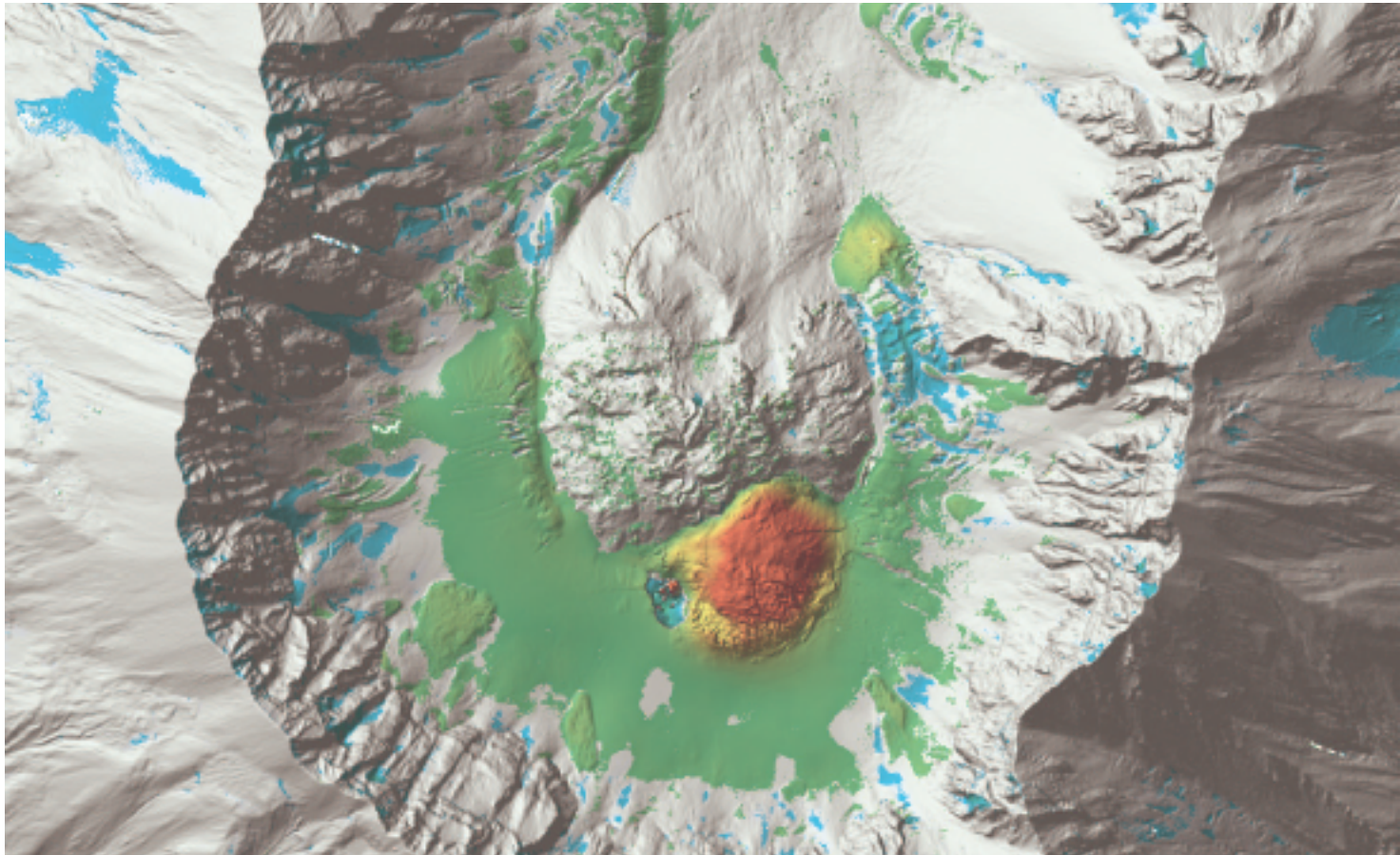




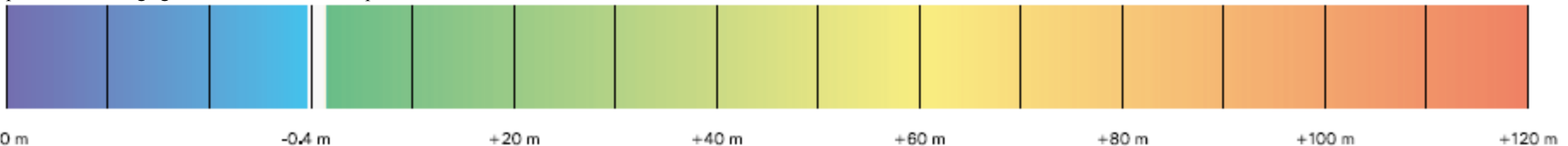


Elevation change at Mt St Helens, September 2003 to October 4-5, 2004

Ralph Haugerud (USGS), David Harding (NASA), Vivian Queija (USGS), Linda Mark (USGS)



<http://vulcan.wr.usgs.gov/Volcanoes/MSH/Eruption04/LIDAR/framework.html>



9-03



<http://vulcan.wr.usgs.gov/Volcanoes/MSH/Eruption04/LIDAR/framework.html>

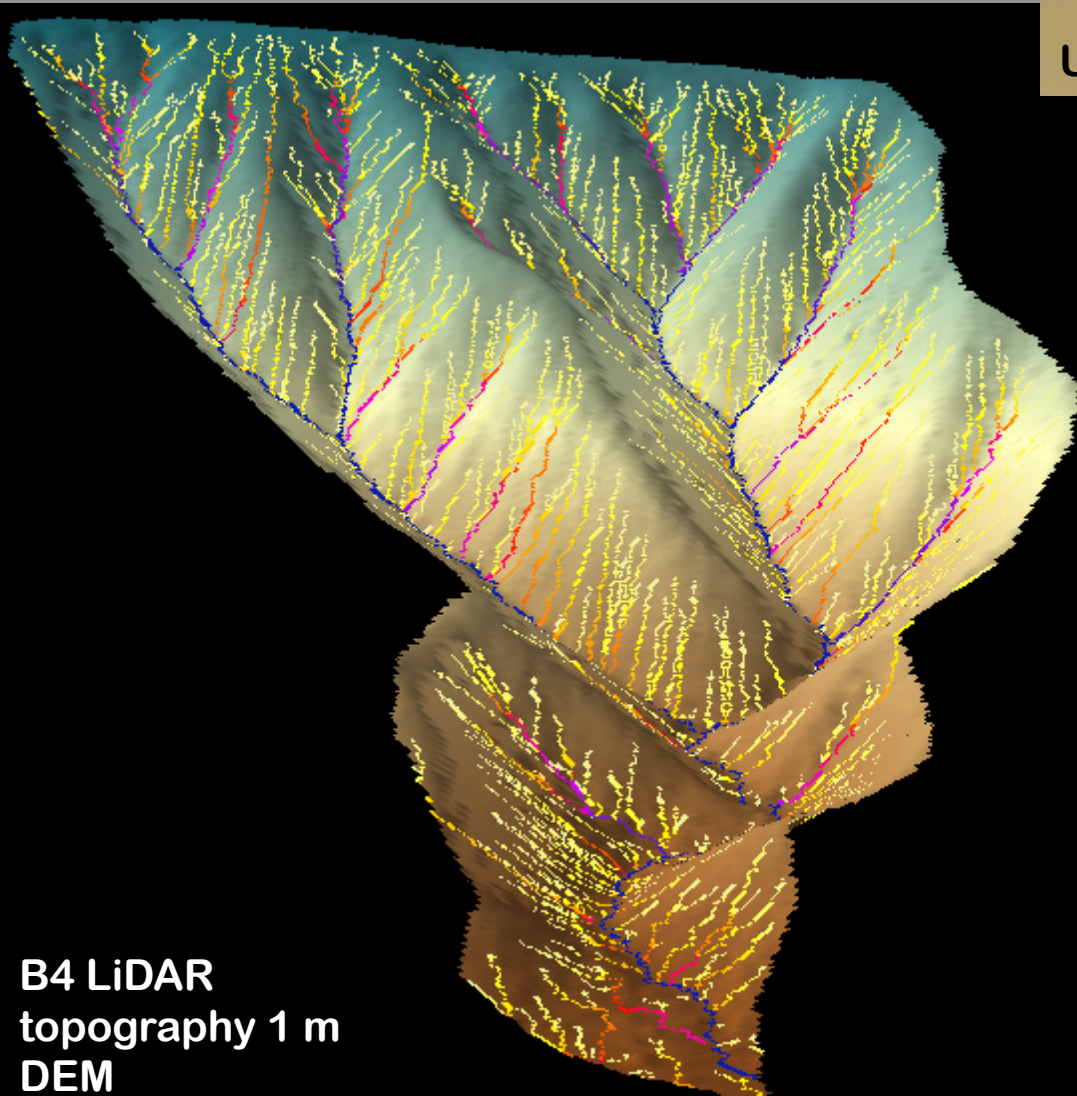
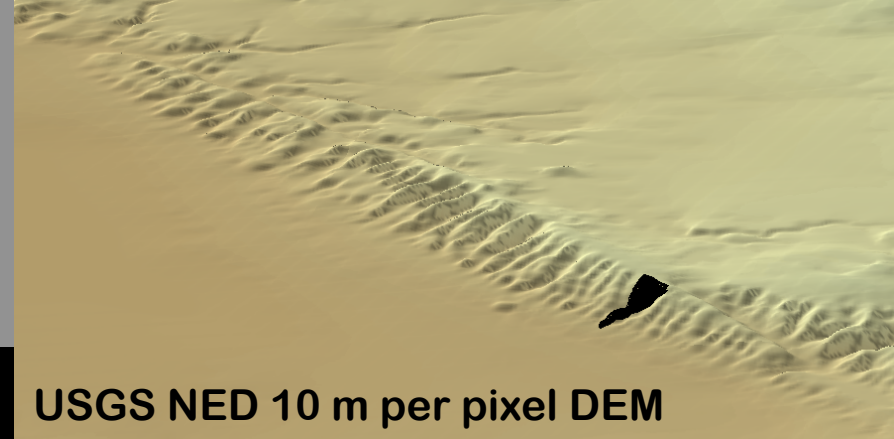




*Port-au-Prince
waterfront produced
from lidar point cloud
data.*

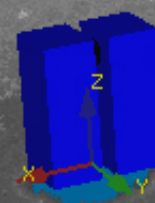
Crosby, SDSC

Measuring Landscape Characteristics at the Appropriate Scale





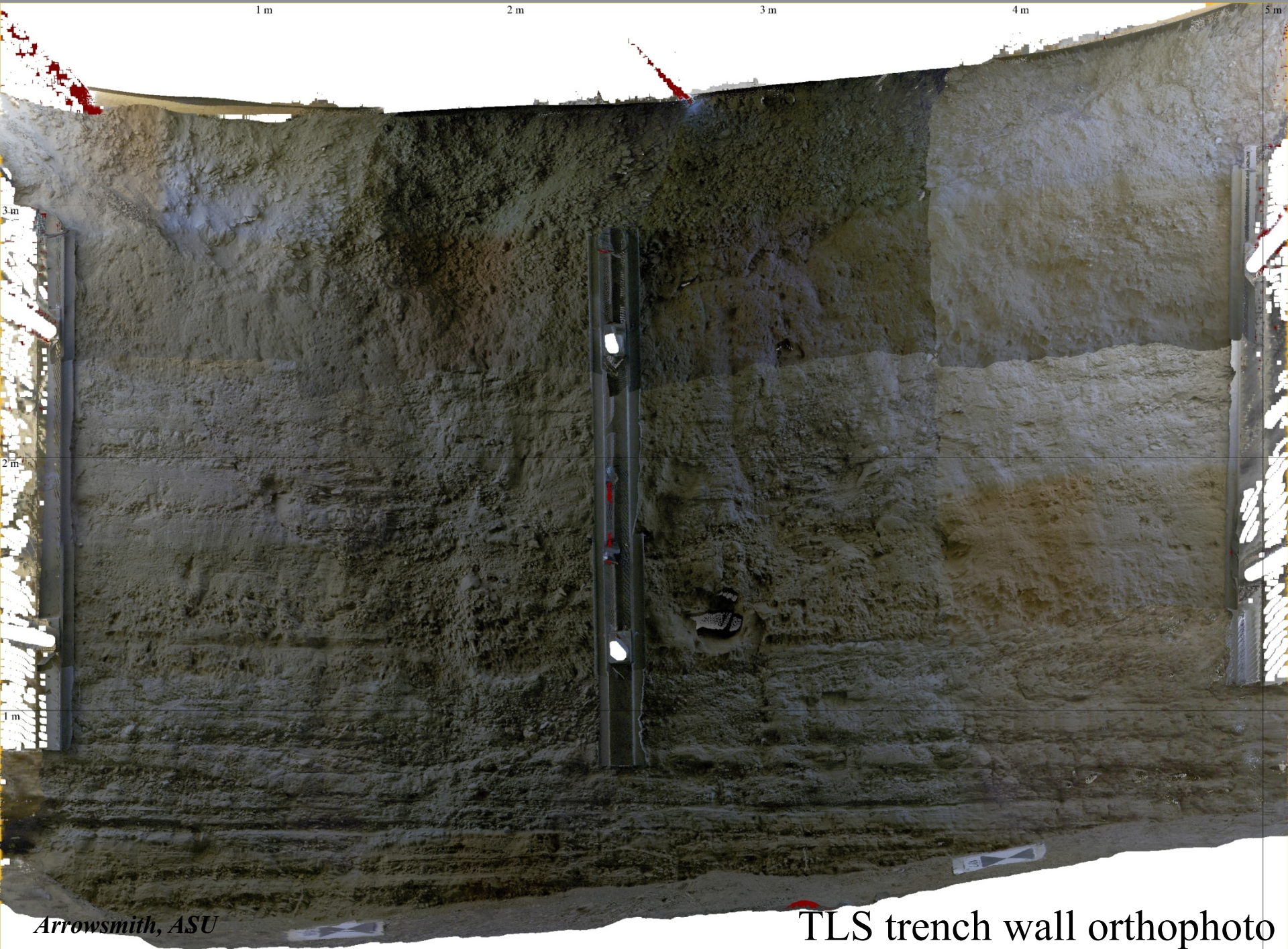






Arrowsmith, ASU





1 m

2 m

3 m

4 m

5 m

3 m

2 m

1 m

Arrowsmith, ASU

TLS trench wall orthophoto

Questions & Comments:

ccrosby@sdsc.edu



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