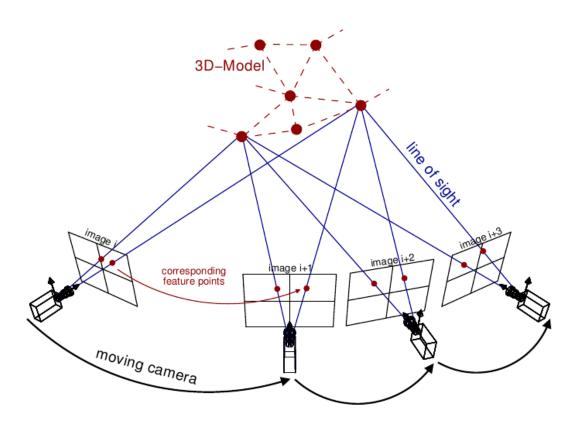
Structure from Motion



- Solves for the scene structure using photographs from a moving camera
- "Structure" = positions and orientations of camera + positions of targets
- Can also solve for camera parameters like focal length, lens distortion

Kinetic depth effect



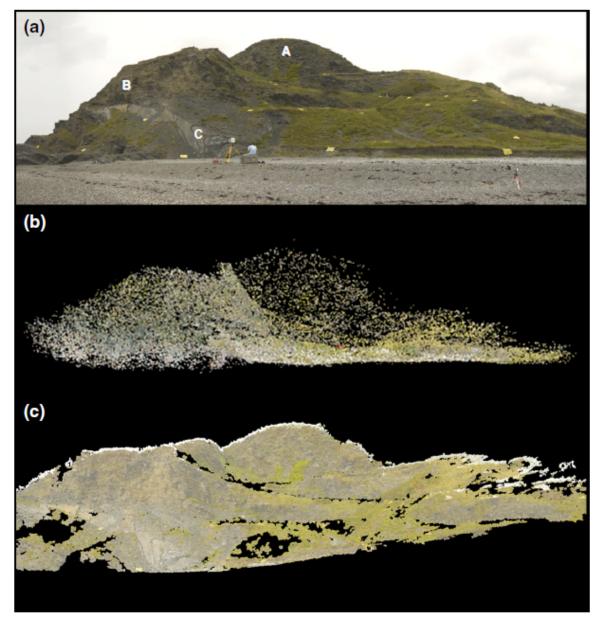
The three-dimensional shape of an object can be perceived when the object is moving relative to the observer

Objects further apart from the observer appear to move more slowly than those that are closer.

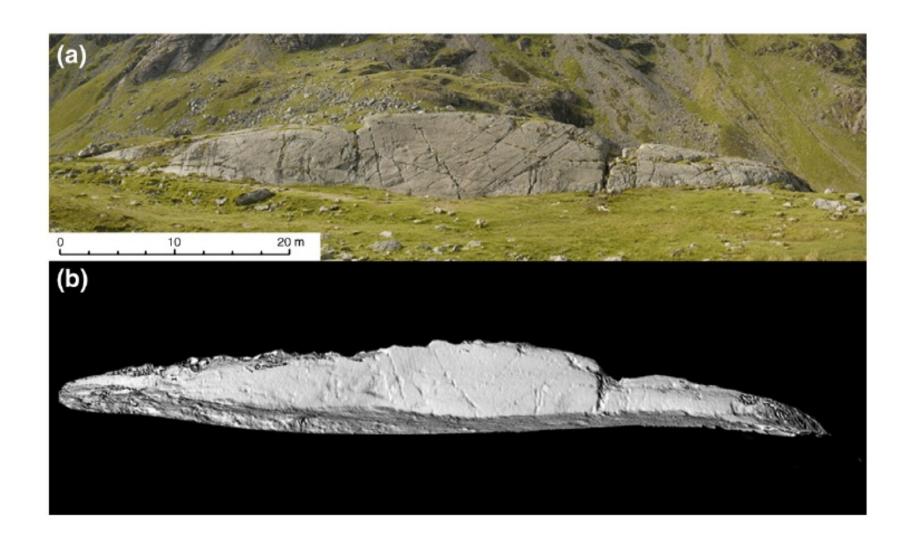
Snavely et al. (2007). Modeling the World from Internet Photo Collections, *International Journal of Computer Vision*



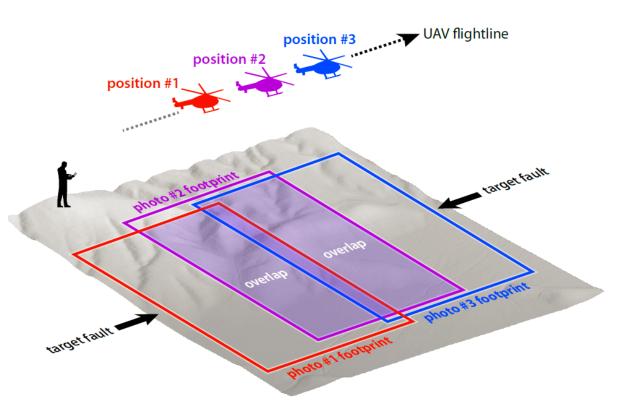
- Development of Scale Invariant Feature Transform (Lowe, 1999)
- Allows common features to be detected even with extreme variations in scale (and viewpoint
- Even works under conditions of partial occlusion and changing illumination
- Improvement on photogrammetry: unordered image aquisition



Westoby et al. (2012). 'Structure-from-Motion' photogrammetry: A low-cost, effective tool for geoscience applications, *Geomorphology*



Westoby et al. (2012). 'Structure-from-Motion' photogrammetry: A low-cost, effective tool for geoscience applications, *Geomorphology*



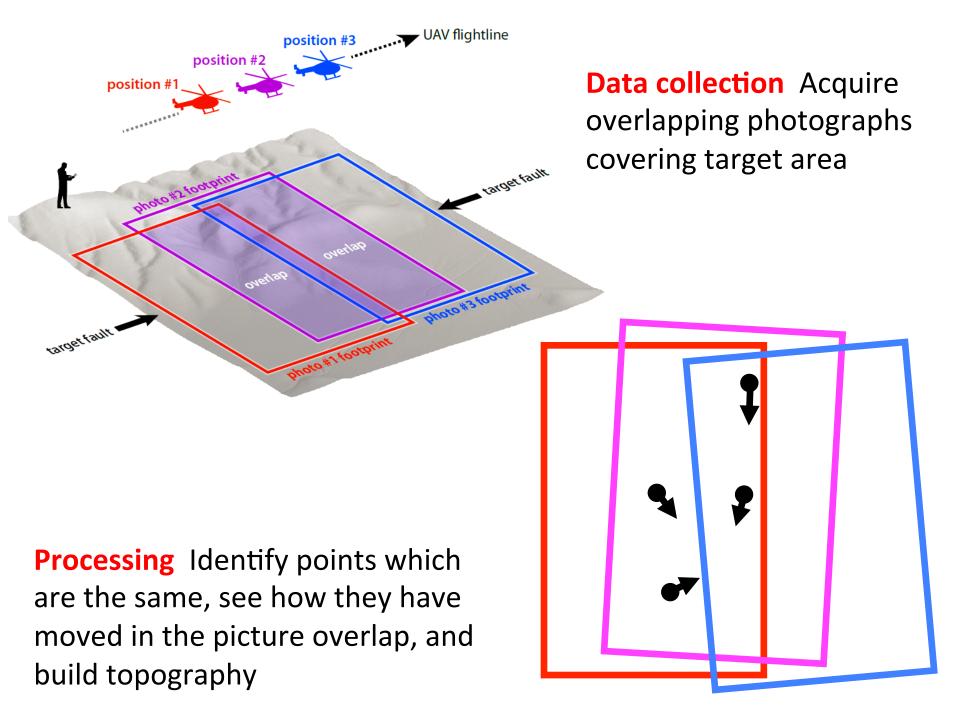
Structure from Motion using cheap airborne platforms

Kendra Johnson, Ed Nissen (Colorado School of Mines)

Ramon Arrowsmith, Sri Saripalli, Emily Kleber, Barrett Salisbury (ASU)

Kate Scharer (USGS), Patrick Williams (SDSU)





Aerial platform

Cost, Payload, Flight time, Ease of deployment and navigation, Robustness to conditions

Camera

Internal GPS, Weight vs Image quality

Survey set-up

Flight path, Platform height, Ground Control Points

Build point cloud

Choice of software package, Cost vs Ease of use, Point density and precision

Derivative products

Aerial platform



Pros once in the air, can follow pre-set flight path. Robust in high wind and can take off and land anywhere. Can carry large SLR camera

Cons needs trained pilot to take-off and land. Needs regular refuelling. Initial costs are high and requires careful maintenance. FAA regulations must be followed.

Aerial platform



Pros easy to self- launch and to pilot. Can cope in moderately windy conditions.

Cons can only carry small cameras and is susceptible to damage during landing. Batteries need frequent replacing/recharging.

Aerial platform



Pros can be deployed at a >100m providing wider field of view. Easy to drag across target area. Can carry quite large cameras. Once in the air can remain there.

Cons difficult to control even in light breezes and impossible in windy conditions.

Aerial platform



Pros can be deployed at a >100m providing wider field of view. Easy to drag across target area. Can carry quite large cameras. Once in the air can remain there. Robust in high wind.



Aerial platform









Camera

Internal GPS, Weight vs Image quality

Survey set-up

Flight path, Platform height, Ground Control Points

Build point cloud

Choice of software package, Cost vs Ease of use

Derivative products

The camera should have one essential feature and one preferable one:

Essential Time lapse setting – remotely takes photo every *x* seconds

Preferable Internal or external GPS tagging

Camera

Internal GPS, Weight vs Image quality





+ve lightweight (300 g)

-ve SD card needs programming, occasionally turns off mid-flight **+ve** high quality photos

-ve heavy (1 kg)

Aerial platform









Camera





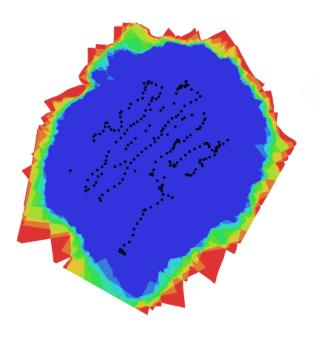
Survey set-up

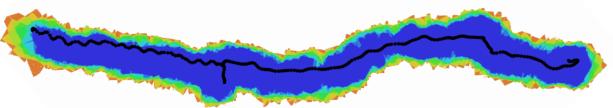
Flight path, Platform height, Ground Control Points

Build point cloud

Choice of software package, Cost vs Ease of use

Derivative products



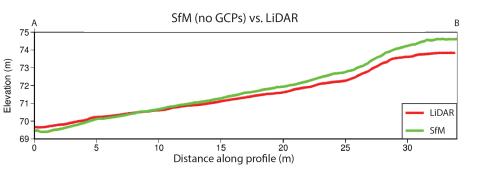


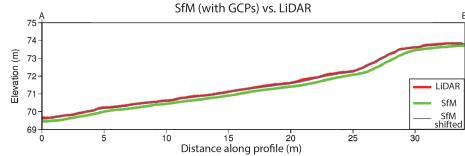
Top: Landers rupture, 1 km x 100 m dataset

Left: Washington fan, 300 m x 300 m dataset

Survey set-up

Flight path, Platform height, Ground Control Points





Aerial platform





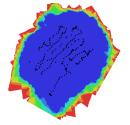




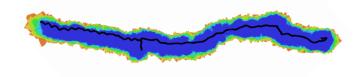
Camera

Survey set-up









Build point cloud

Choice of software package, Cost vs Ease of use

Derivative products

Free option

Bundler builds sparse point cloud

CMVS + PVMS2 builds dense point cloud

MATLAB georeferences point cloud with rigid body transformation + scale

Commercial option

Agisoft Photoscan Pro

costs \$550 for academic licence

builds georeferenced point cloud using camera GPS stamps (+ optional GCPs)

Build point cloud

Choice of software package, Cost vs Ease of use



Commercial option

Agisoft Photoscan Pro

costs \$550 for academic licence

builds georeferenced point cloud using camera GPS stamps (+ optional GCPs)

Dell Alienware PC, 32GB RAM, Nvidia GeForce GTX 670 = \$3,000

Build point cloud

Choice of software package, Cost vs Ease of use

Aerial platform







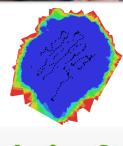


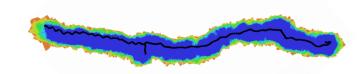
Camera





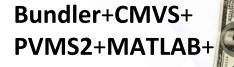
Survey set-up





Build point cloud





Derivative products

Aerial platform







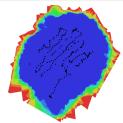


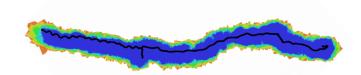
Camera





Survey set-up





Build point cloud



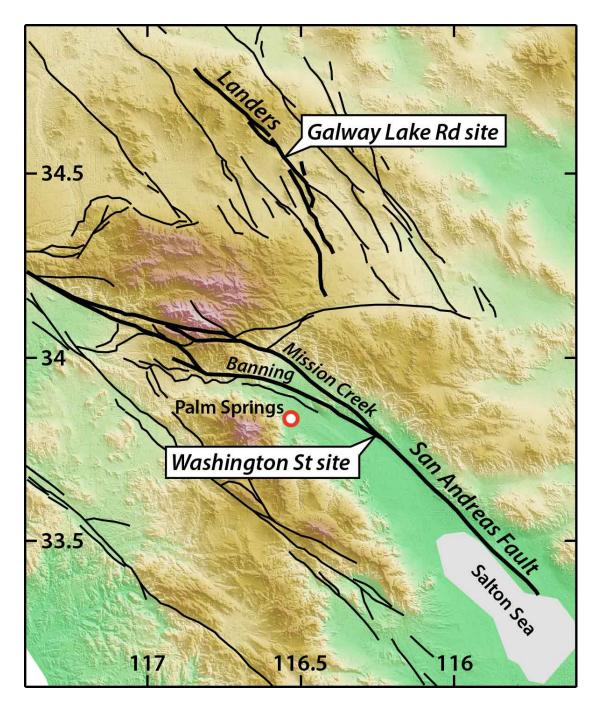


Derivative products









Galway Lake Rd site

Covers part of the 1992 Landers earthquake rutpure.

Here we are testing SfM's potential as a rapid response mapping tool (e.g. aftermath of an earthquake).

Existing TLS dataset

Washington St site

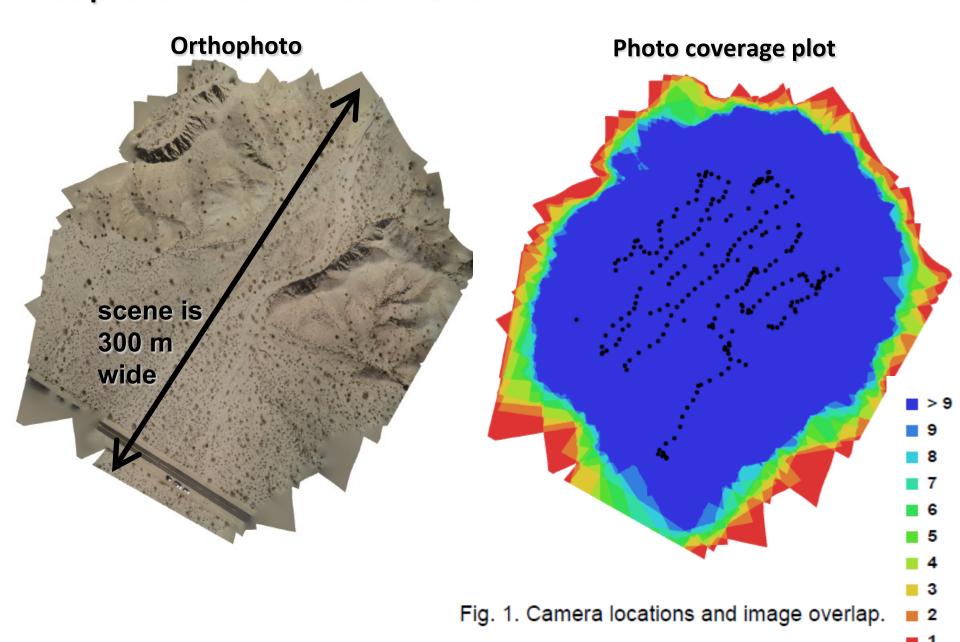
Argument over which of two SAF strands is active.

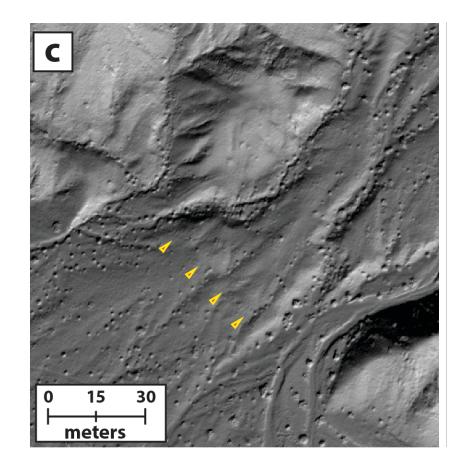
Small meter-scale streams offsets >> slip in last event

Larger alluvial fan offsets >> long term slip rates

Existing airborne LiDAR data

230 photos taken in about one hour

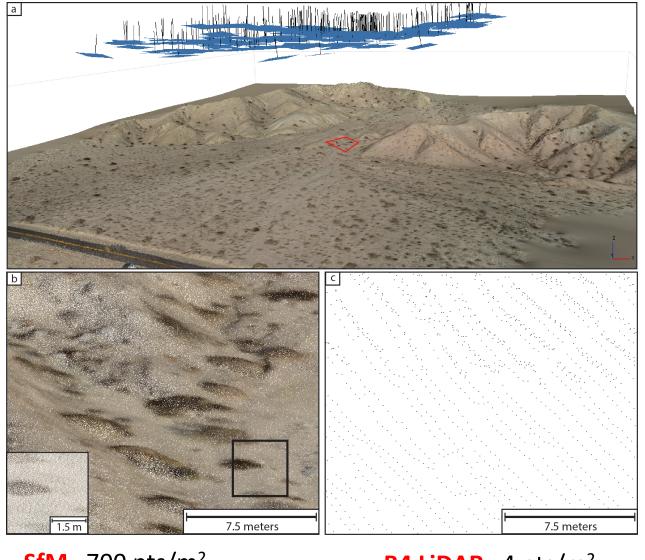




SfM 5 cm resolution DEM

B4 LiDAR 0.5 - 1 m resolution

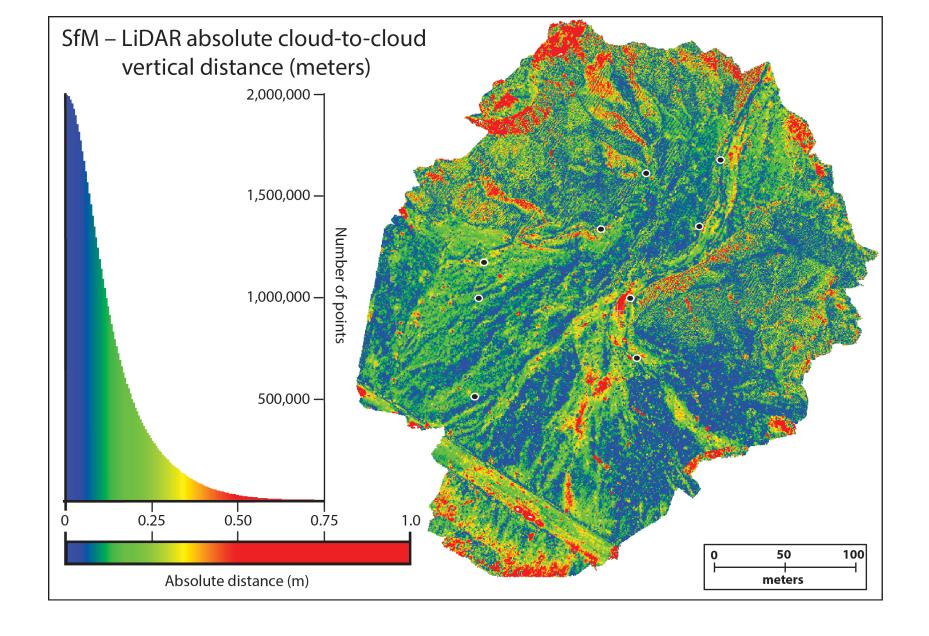
Kendra Johnson et al., in prep.



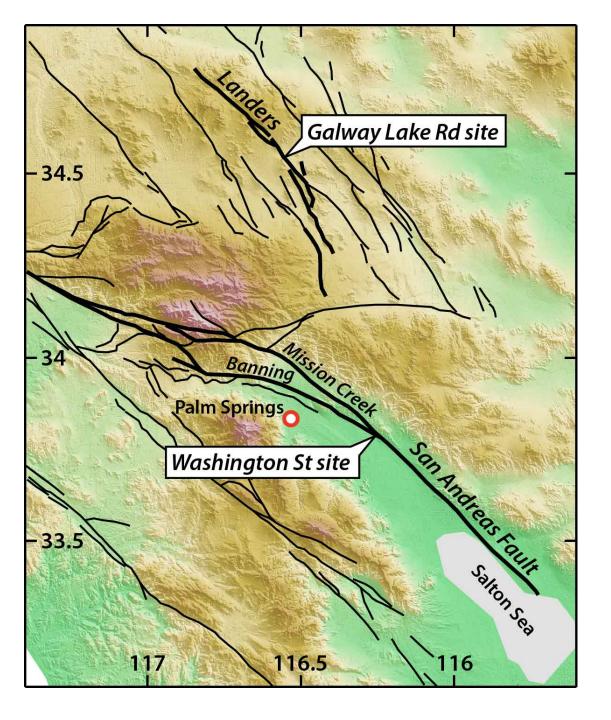
SfM 700 pts/m²

B4 LiDAR 4 pts/m²

Kendra Johnson et al., in prep.



Kendra Johnson et al., in prep.



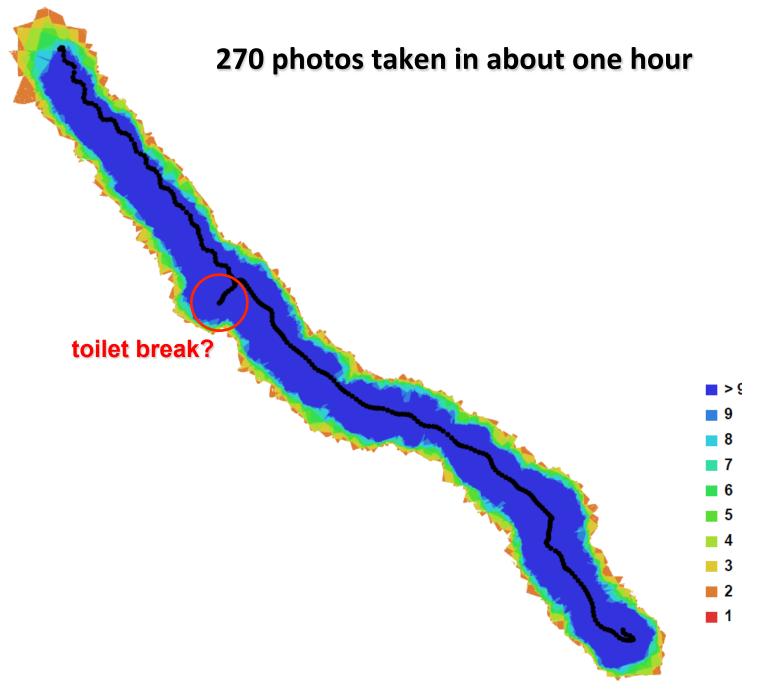
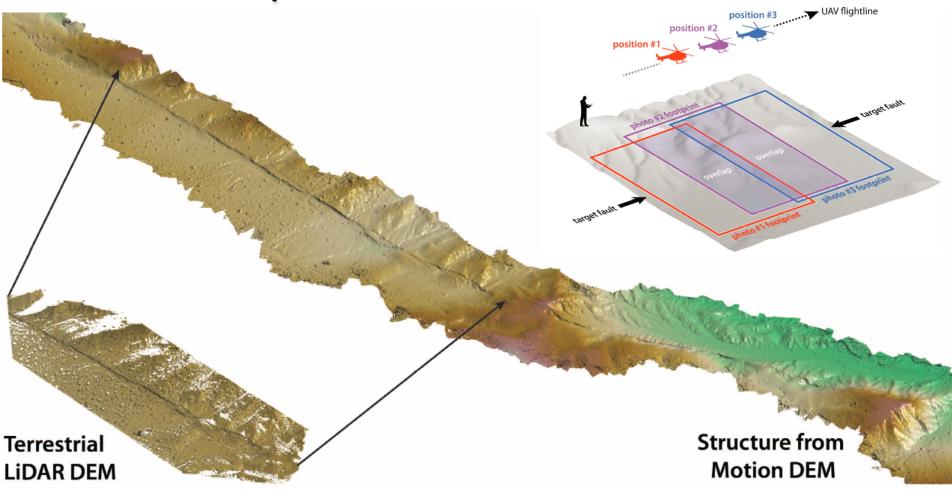


Fig. 1. Camera locations and image overlap.

270 photos taken in about one hour



TLS data took two days to collect