

# Buying lidar data

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# How to buy lidar data

- You know somebody...  
A known quantity. Easiest
- Advertise for bids  
Maybe you don't know as much as you think
- NCALM (<http://www.ncalm.org/>)  
NSF sponsored, partly subsidized, limited capacity
- Participate in a consortium  
Economies of scale, in-place contracting structure,  
community of experience  
Geographically limited
- Start your own consortium  
Advertise for bids  
...

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lidar data vendors - Google Search

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Google lidar data

Web Show options...

**Airborne LIDAR solutions**  
[www.terrasolid.fi](http://www.terrasolid.fi) Innovative software and mobile point clouds

**Galileo Group Inc.**  
[www.galileo-gp.com](http://www.galileo-gp.com) Lidar Sensor Lidar/Hyperspectral Fusion

**LiDAR Exploitation Tools**  
[www.appliedimagery.com](http://www.appliedimagery.com) Quickly exploit huge LIDAR & 3D datasets

**Scholarly articles for lidar data vendors**  
 ... forest canopy fuel parameters  
 Andersen - Cited by 58  
 Estimating relative lidar data  
 Latypov - Cited by 26  
 Voxels as a representation of  
 Stoker - Cited by 10

[PDF] A Guide to LIDAR Data

Done

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http://lidar.cr.usgs.gov

LIDAR Websites and References

<http://www.inphoUSA.com>

**INPHO**  
<http://www.inphoUSA.com>

**LandAir Mapping Inc.**  
<http://www.landairmap.com>

**Lasemap Image Plus**  
[http://www.lasemap.com/laserM/home\\_en.htm](http://www.lasemap.com/laserM/home_en.htm)

**LAStools**  
<http://www.cs.unc.edu/~isenburg/lastools/>

**libLAS**  
<http://liblas.org/>

**LiDAR Data**  
<http://www.lidardata.com>

**LIDAR Services (UK)**  
<http://www.lidar.co.uk>

**LIDAR Services International Inc.**  
<http://www.lidarservices.ca>

**LiDARXCHANGE**  
<http://www.lidarxchange.com>


**M7 Visual Intelligence LP**  
<http://www.visidata.com>

**MAPPS**  
<http://www.manns.org/>

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http://www.ncalm.org

NCALM - NSF supported Center for Airborne Laser Mapping



- [About the Center](#)
- [Proposal Development](#)
- [Current Projects](#)
- [People](#)
- [Data Distribution](#)

## About the Center

### Background

The National Science Foundation (NSF) has created a research center to support the use of airborne laser mapping technology in the scientific community. The NSF supported Center for Airborne Laser Mapping (NCALM) is operated jointly by the Department of Civil & Coastal Engineering, College of Engineering, University of Florida (UF) and the Department of Earth and Planetary Science, University of California-Berkeley (UCB). NCALM uses the Airborne Laser Swath Mapping (ALSM) system jointly owned by UF and Florida International University (FIU), based at the UF Geosensing Engineering and Mapping (GEM) Research Center. The state-of-the-art laser surveying instrumentation and GPS

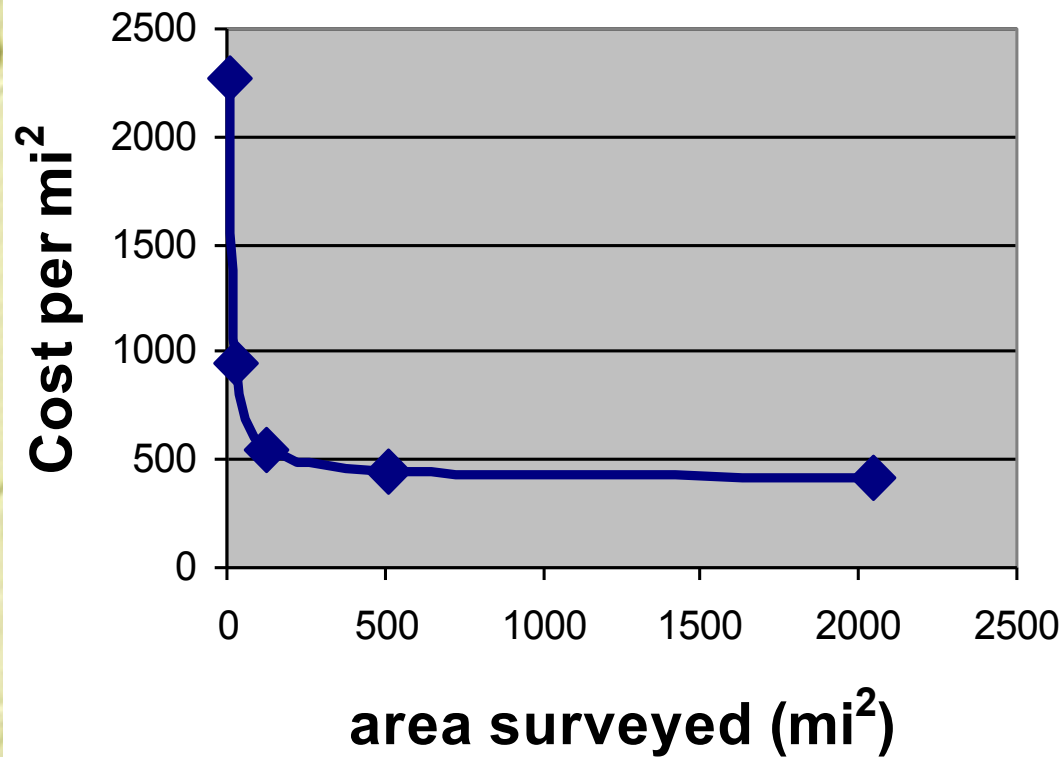


# Specifications

- Where
- When (acquisition, lag to delivery)
- Spatial reference framework
- Ground control (procedures, #, quality)
- Instrument
- Data density and completeness
- Accuracy
- Data products to be delivered (kind, file formats, file naming)
- Acquisition conditions
  - Sky: PDOP, # satellites in view, solar flares, airport operations
  - Ground: leaves, standing water, snow cover, tides
- Data ownership

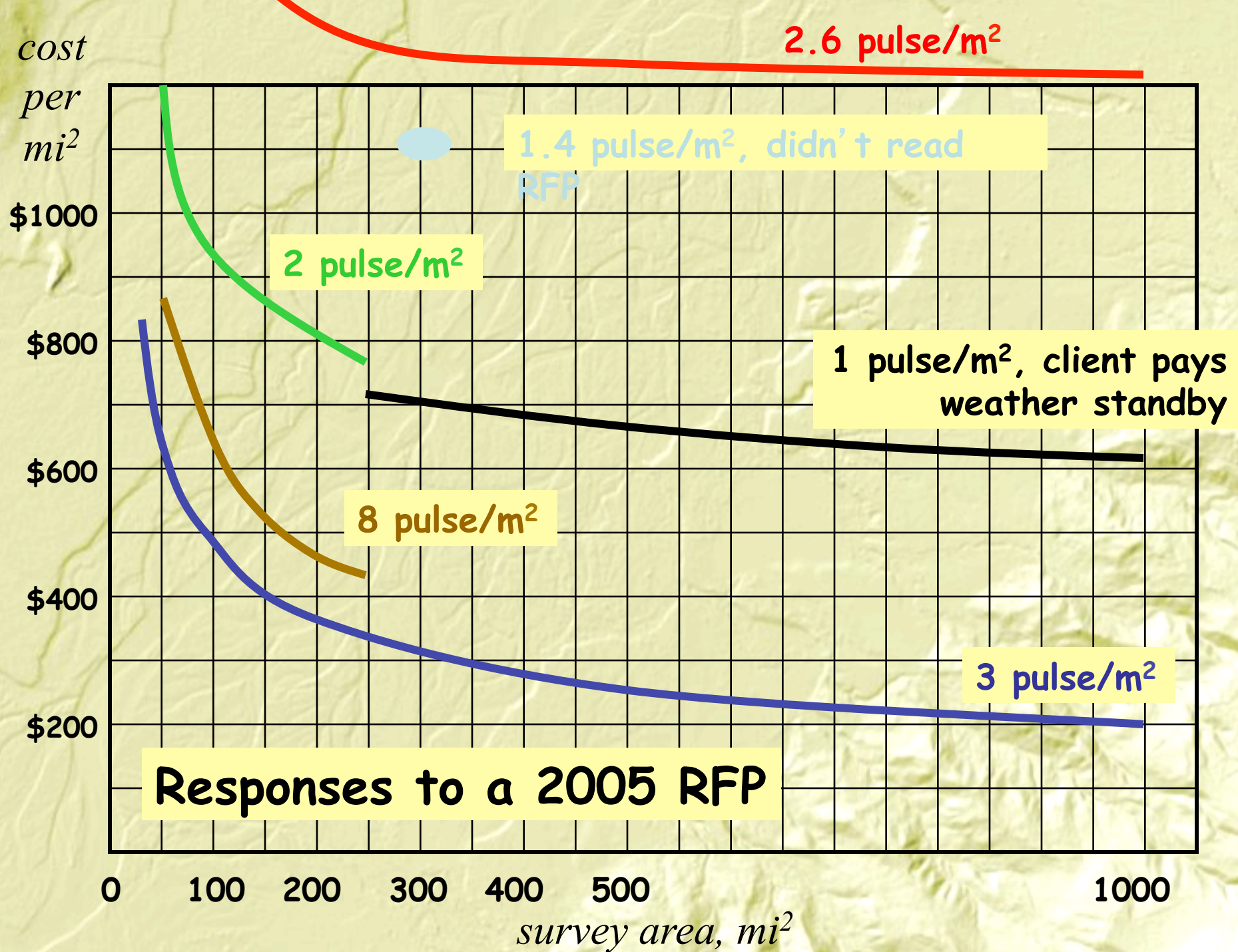
see *A proposed specification for lidar surveys in the Pacific Northwest*, in the course materials





- **\$21K mobilization**
- **\$400/mi² raw cost**
- **Half-swath selvedge**
- **2:1 rectangles**

Costs for an ideal survey





## Recent PSLC contract with Watershed Sciences

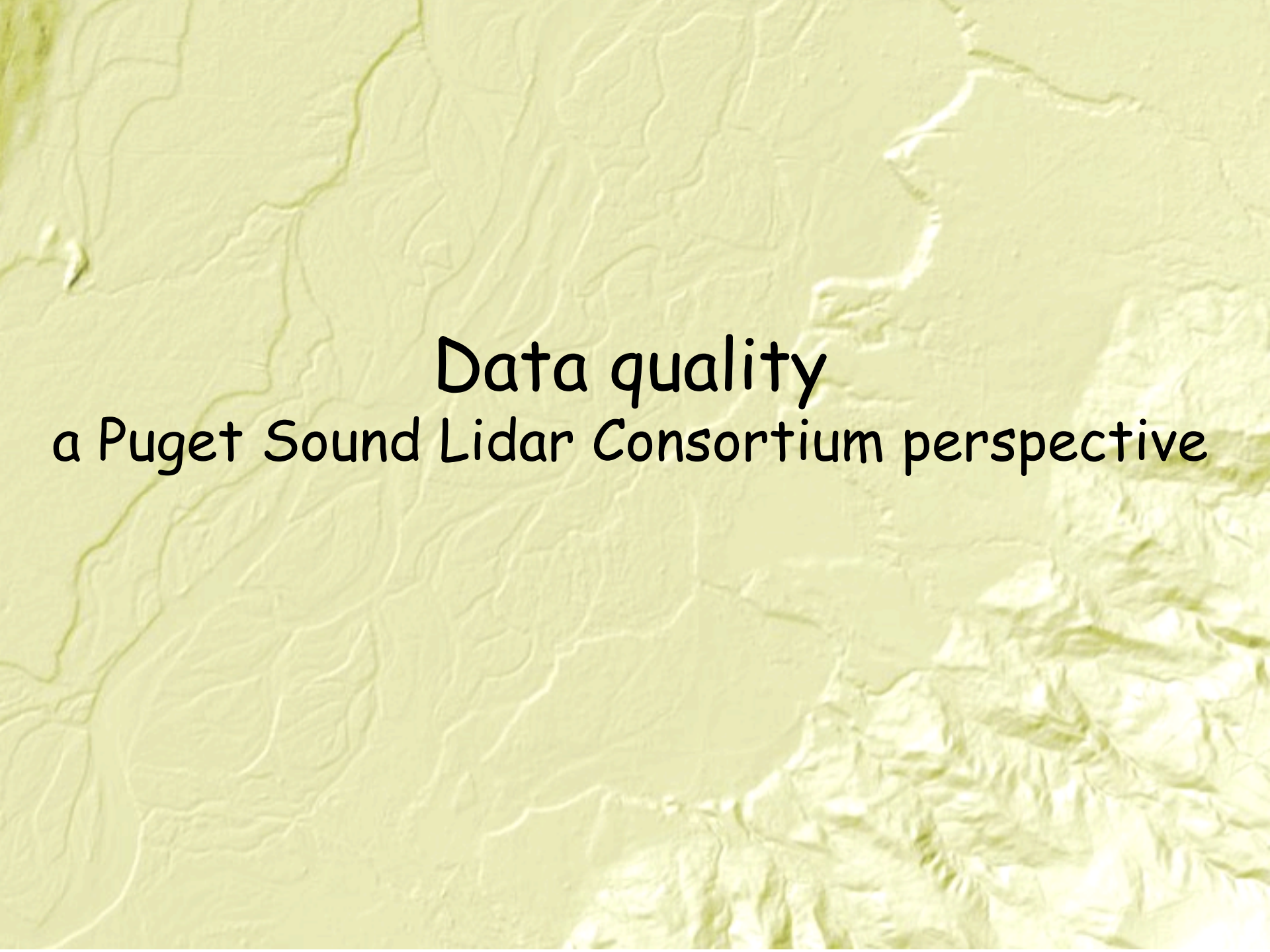
- 50-100 sq mi<sup>2</sup>: \$943/mi<sup>2</sup>     \$420/km<sup>2</sup>
- 100-150 mi<sup>2</sup>: \$704/mi<sup>2</sup>
- 150-200 mi<sup>2</sup>: \$592/mi<sup>2</sup>
- 200-250 mi<sup>2</sup>: \$521/mi<sup>2</sup>
- > 250 mi<sup>2</sup>: \$472/mi<sup>2</sup>     \$210/km<sup>2</sup>

no mobilization fee

includes

5% to Kitsap County

5% to Regional Council

The background of the slide is a topographic map of a mountainous region, likely in the Pacific Northwest. The map is rendered in shades of yellow and green, with contour lines indicating elevation. The terrain is rugged, with numerous peaks and valleys. The text is overlaid on the map, centered in the upper half of the slide.

# Data quality

## a Puget Sound Lidar Consortium perspective



# Outline

- Usability, Completeness, Accuracy
- A QA protocol: 3 analyses
  - Test against ground control
  - Examine images of bare-earth surface model
  - Evaluate internal consistency
- What accuracy do we need? Effects of correlated errors

# Usability

- Report of Survey is complete and correct
- Formal metadata are complete and correct
- Consistent, correct, and correctly labeled spatial reference framework
- Consistent file names and file formats
- Usable tiling scheme

*can calculate names of adjoining tiles*



# Usability, continued

- Fully populated data attributes  
*GPS week OR Posix time*
- Consistent calibration
- Consistency between data layers
- No unnecessary artifacts in surface models

# Completeness

- **Complete coverage**

*Filling gaps requires remobilization,  
thus is very expensive*

- Adequate data density
- Adequate swath overlap

*These are what we pay for*



# Accuracy *is complicated*

- Accuracy of point measurements

*What the vendor can be held responsible for*

*Evaluation requires abundant, expensive GCPs*

- Accuracy of DEM

*What we care about*

*Evaluation requires abundant, expensive GCPs*

# DEM error

To make bare-earth DEM:

- 1) Measure XYZ of points
- 2) Classify points as ground or not-ground
- 3) Interpolate ground points to continuous surface

DEM error  $\approx$

$$\left[ \begin{aligned} &(\text{measurement error})^2 \\ &+ (\text{classification error})^2 \\ &+ (\text{interpolation error})^2 \end{aligned} \right]^{1/2}$$

*small,  $\leq 10$  cm*

*large in forested  
terrain*

*ditto*

Rule of thumb:

internal DEM reproducibility  
= 1.5–2 x Z measurement reproducibility



# Accuracy *is complicated*

- Accuracy of point measurements
  - What the vendor can be held responsible for*
  - Evaluation requires abundant, expensive GCPs*
- Accuracy of DEM
  - What we care about*
  - Evaluation requires abundant, expensive GCPs*
- Reproducibility (consistency) of point positions
  - Can be cheaply evaluated from swath overlaps*
  - Provides lower bound on measurement accuracy*
- Reproducibility (consistency) of DEM
  - Can be cheaply estimated from swath overlaps*
  - Provides lower bound on surface model accuracy*



# PSLC QA protocol: 3 analyses

1. Test against ground control points (GCPs)
2. Look at large-scale shaded-relief images
3. CONSISTENCY analysis of swath to swath reproducibility, with completeness inventory

*Extensive automated processing effectively tests for consistent file formats and file naming*

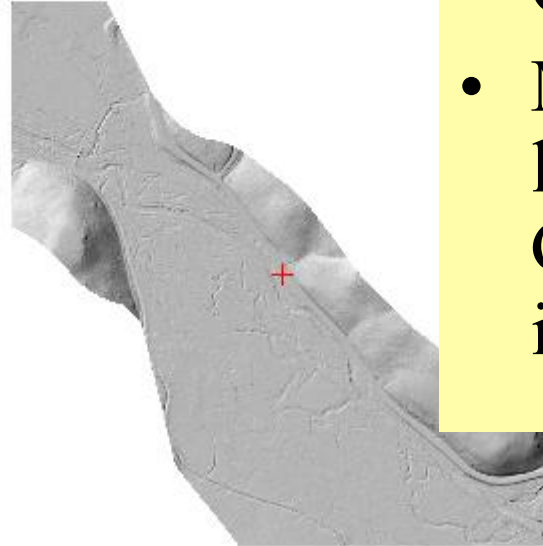


# Test against C

- We use existing GCPs (cost / benefit for new GCPs is too high)
- Must filter for landscape change, GCPs on corners, GCPs in vaults, etc.

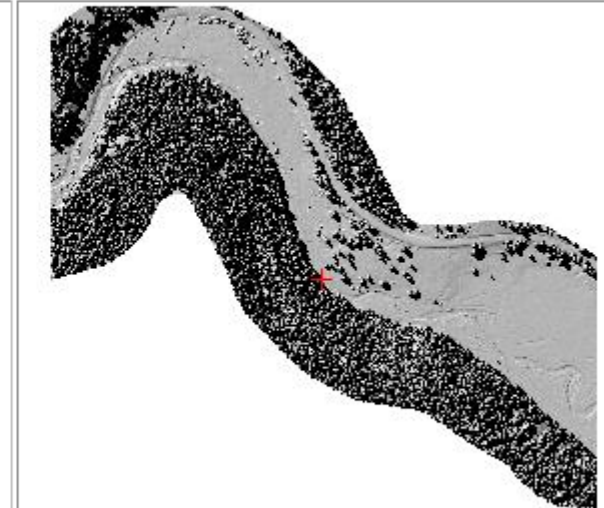
GCP ID: doi10  
QQuad: mflupper  
GCP Elev (ft): 1220.946  
DEM Elev (ft): 1221.077  
GCP - BE DEM (ft): -0.131  
GCP - BE DEM (cm): -3.990  
Curvature: 9.082  
Slope: 3.693

Included: No

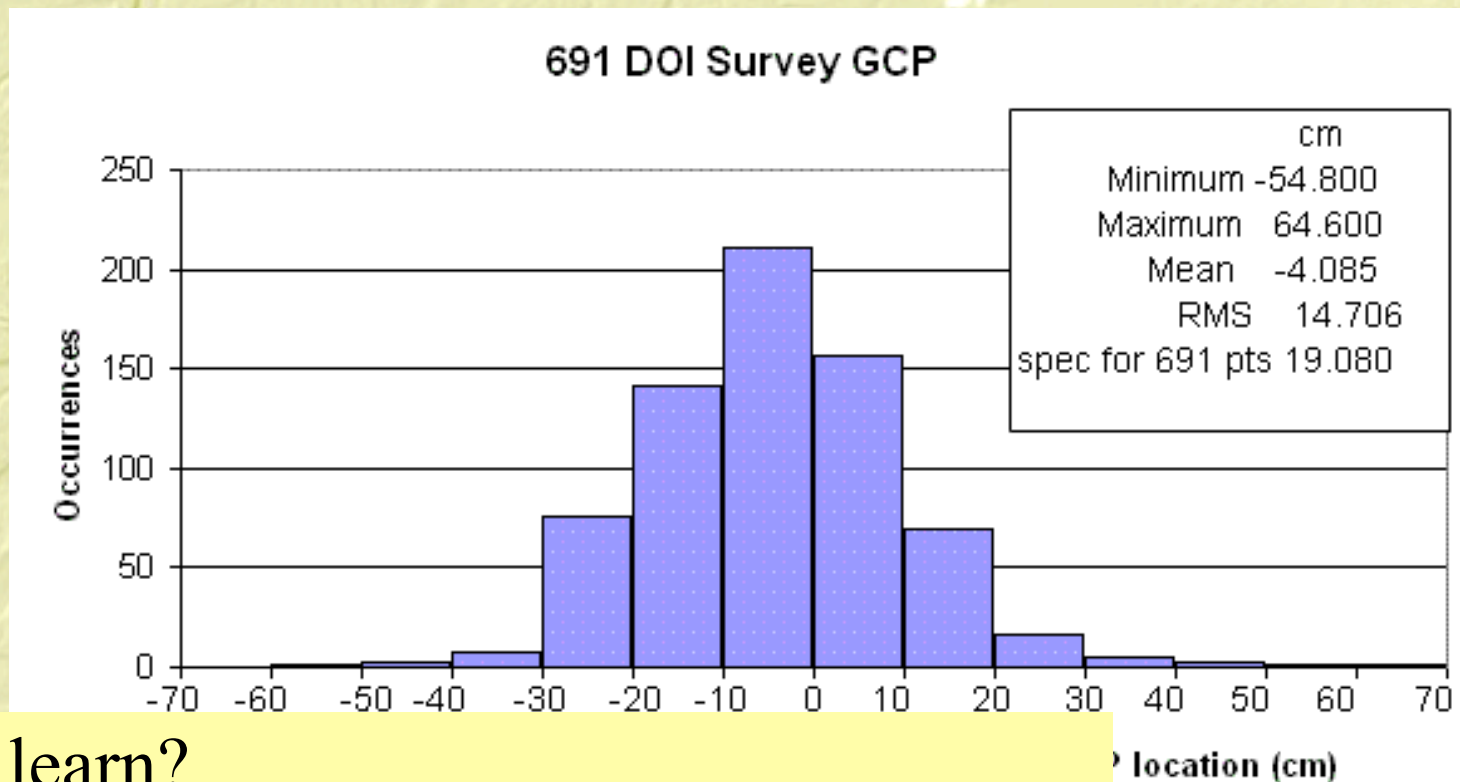


GCP ID: doi11  
QQuad: mflupper  
GCP Elev (ft): 1202.886  
DEM Elev (ft): 1203.228  
GCP - BE DEM (ft): -0.342  
GCP - BE DEM (cm): -10.429  
Curvature: 1.361  
Slope: 7.967

Included: Yes



# Test against GCPs

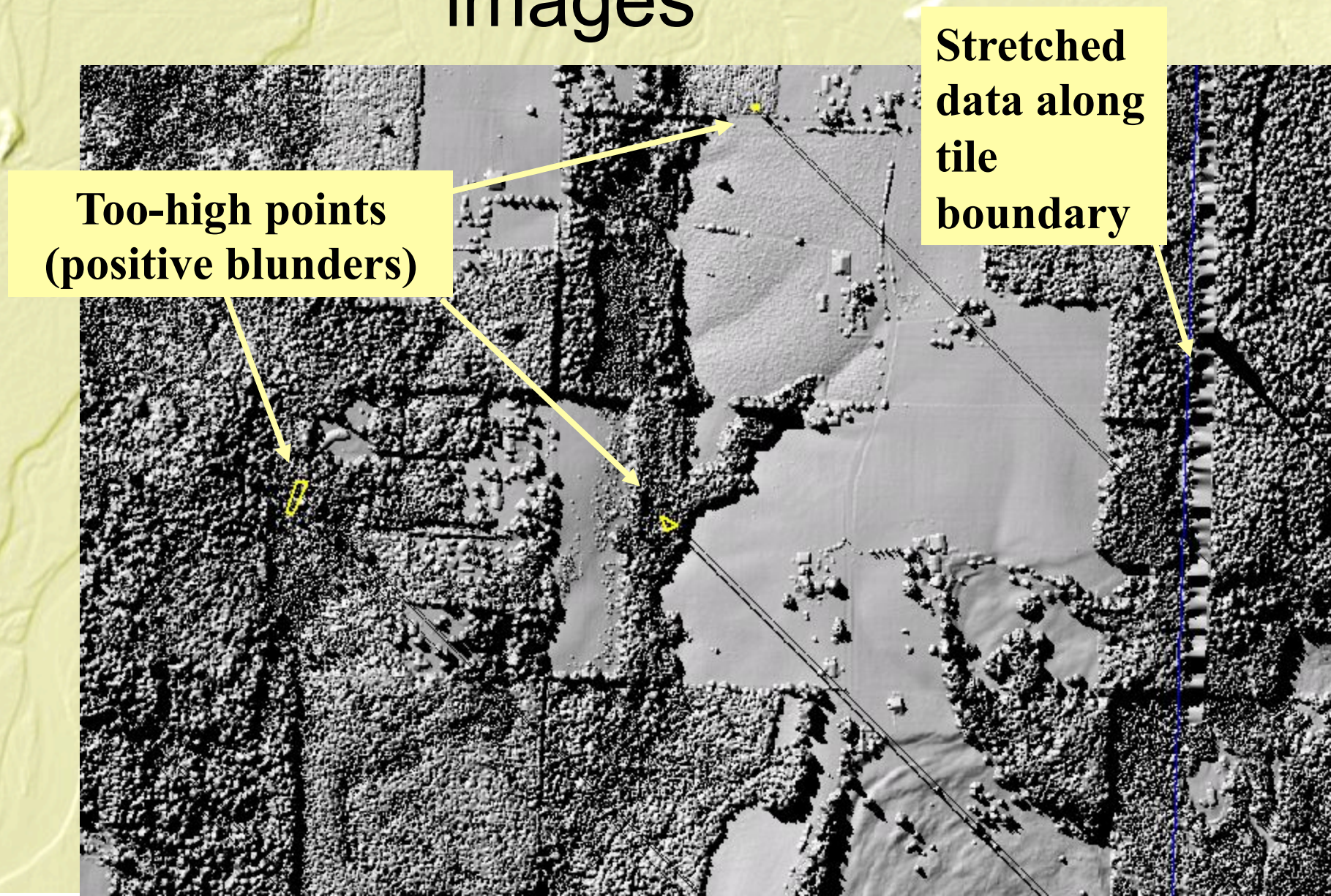


What do we learn?

- Confirm absolute accuracy, typically with low confidence
- Identify undocumented and misdocumented spatial reference frameworks

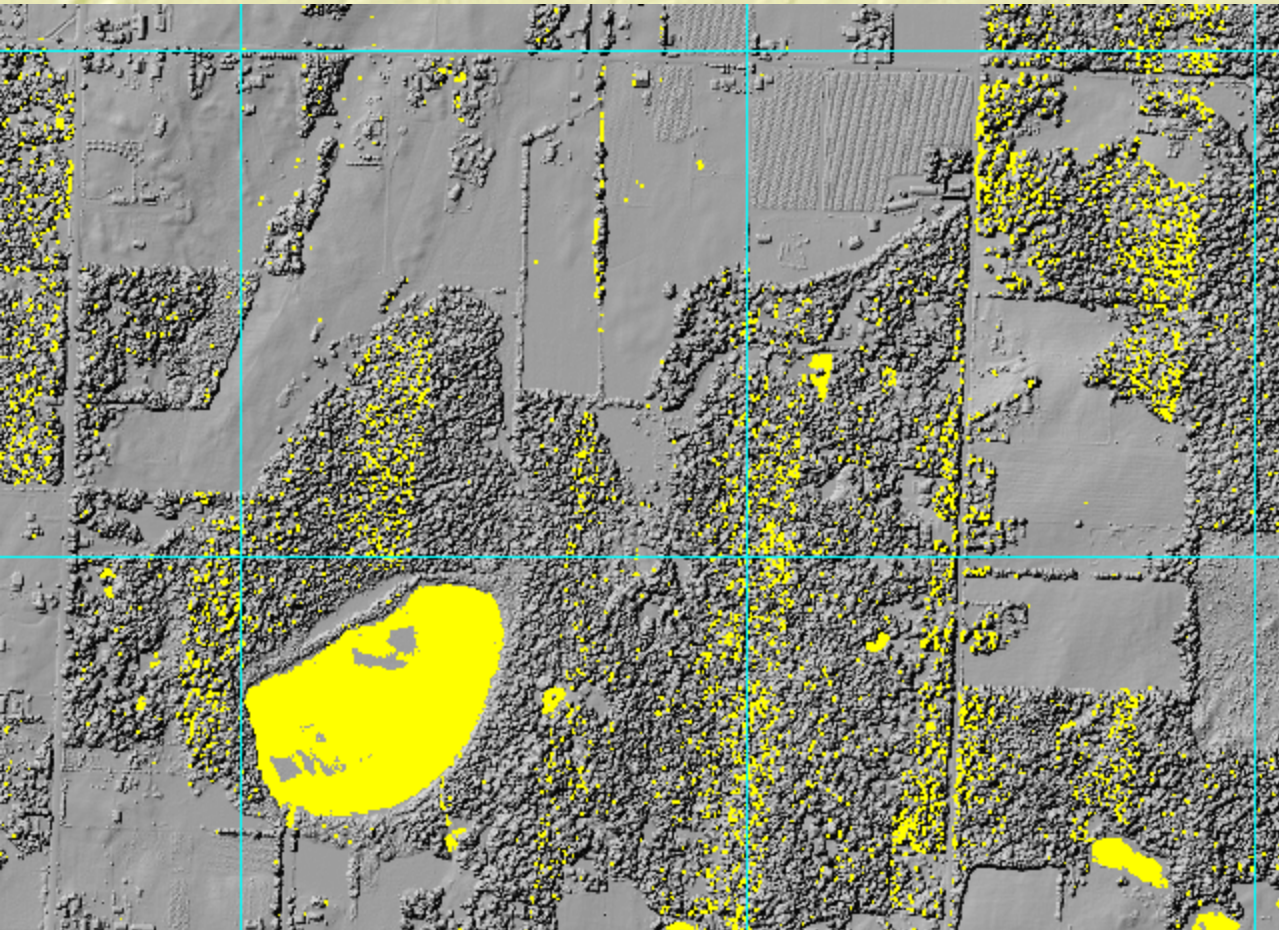


# Look at large-scale shaded-relief images





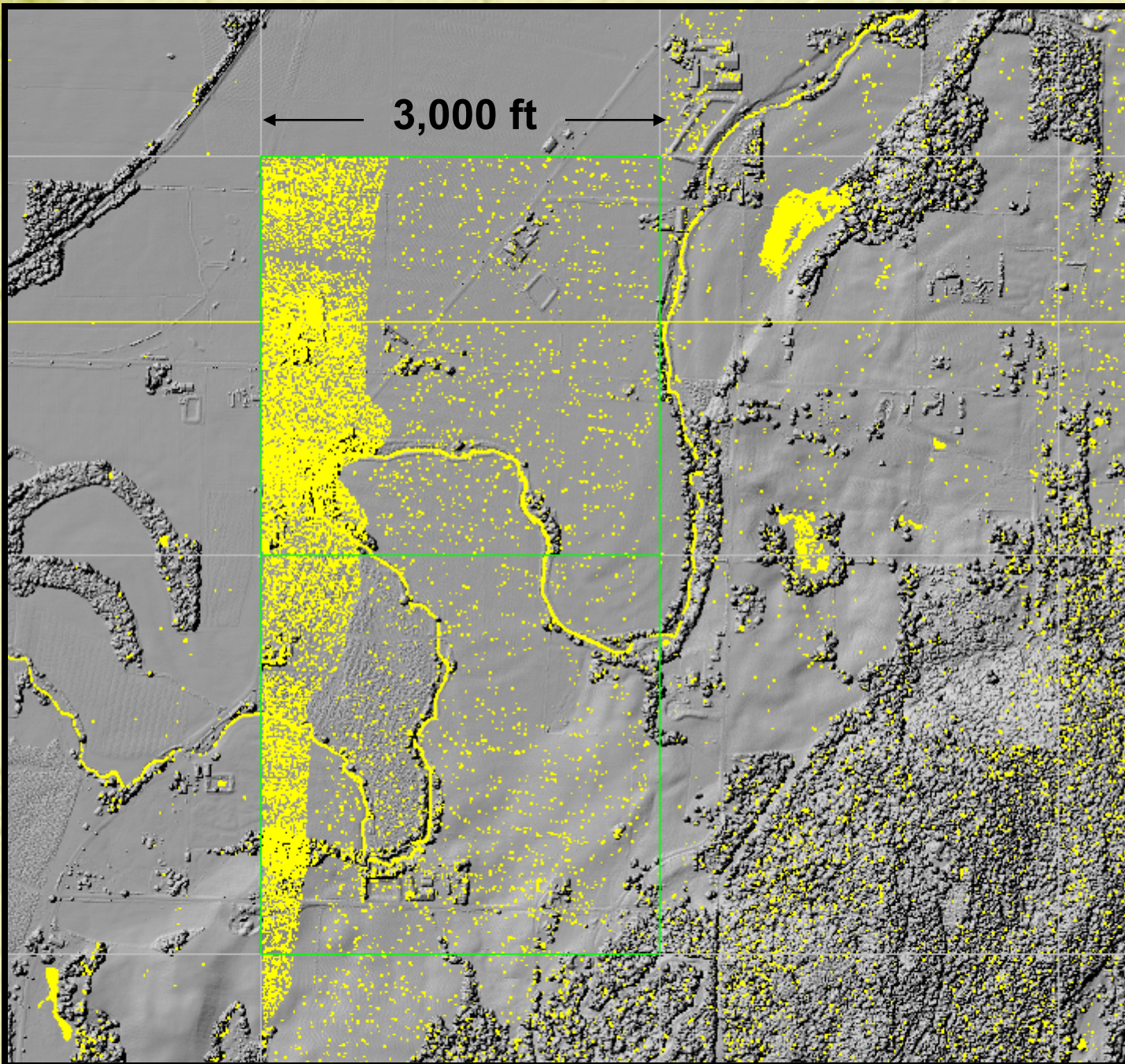
← 3,000 ft →



- **Highest-hit surface, voids = NoData.**
- **6-ft raster**
- **Voids for open water (specular reflection) and in forest (off-nadir shadowing by canopy)**

**GOOD**



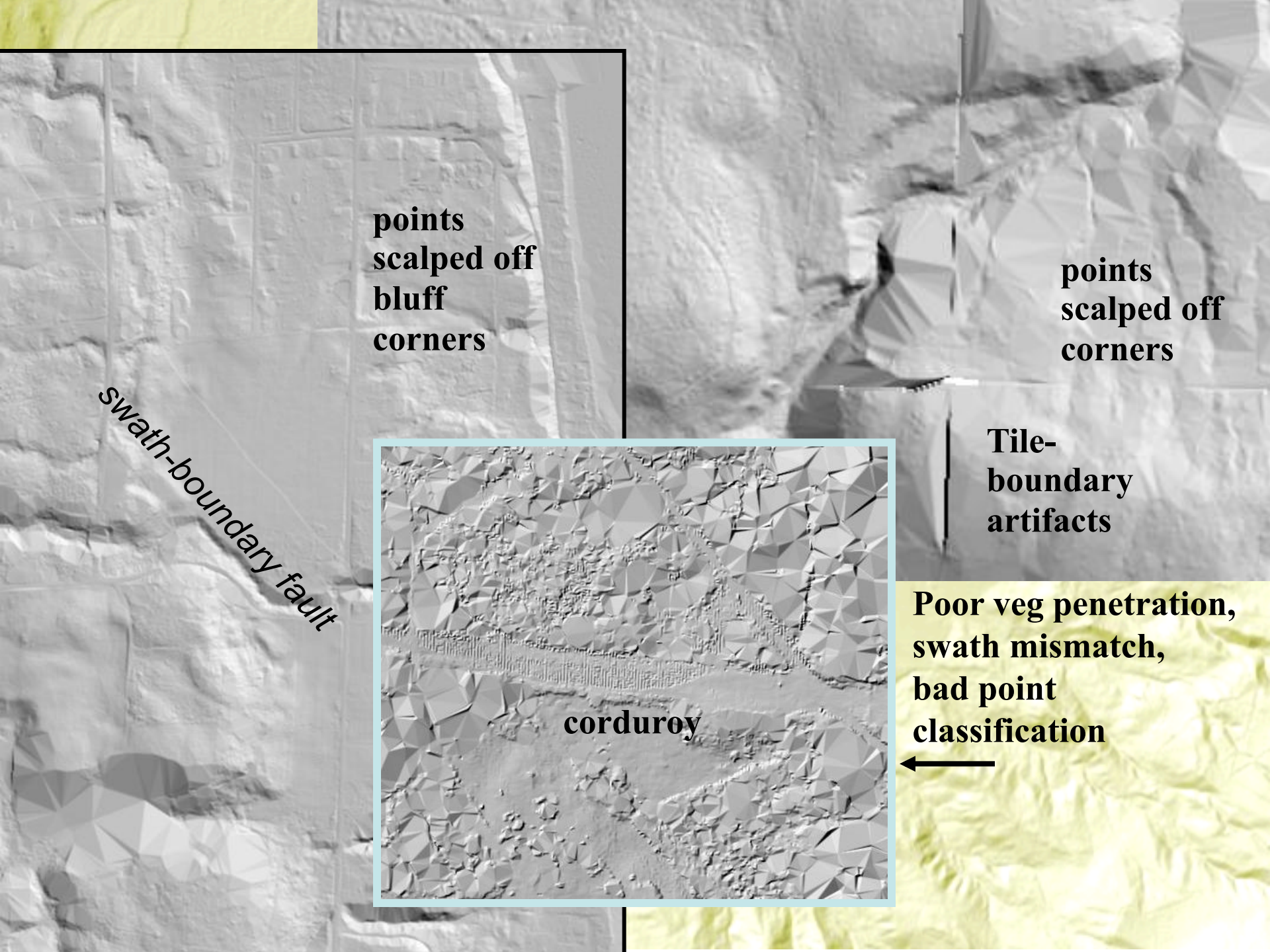


Observation:  
Voids end at  
tile bound-  
aries, not  
only at swath  
margin.

Inference:  
Data omitted  
on tile-by-  
tile basis

**BAD**





**points  
scalped off  
bluff  
corners**

**points  
scalped off  
corners**

**Tile-  
boundary  
artifacts**

**Poor veg penetration,  
swath mismatch,  
bad point  
classification**



**swath-boundary fault**

**corduroy**





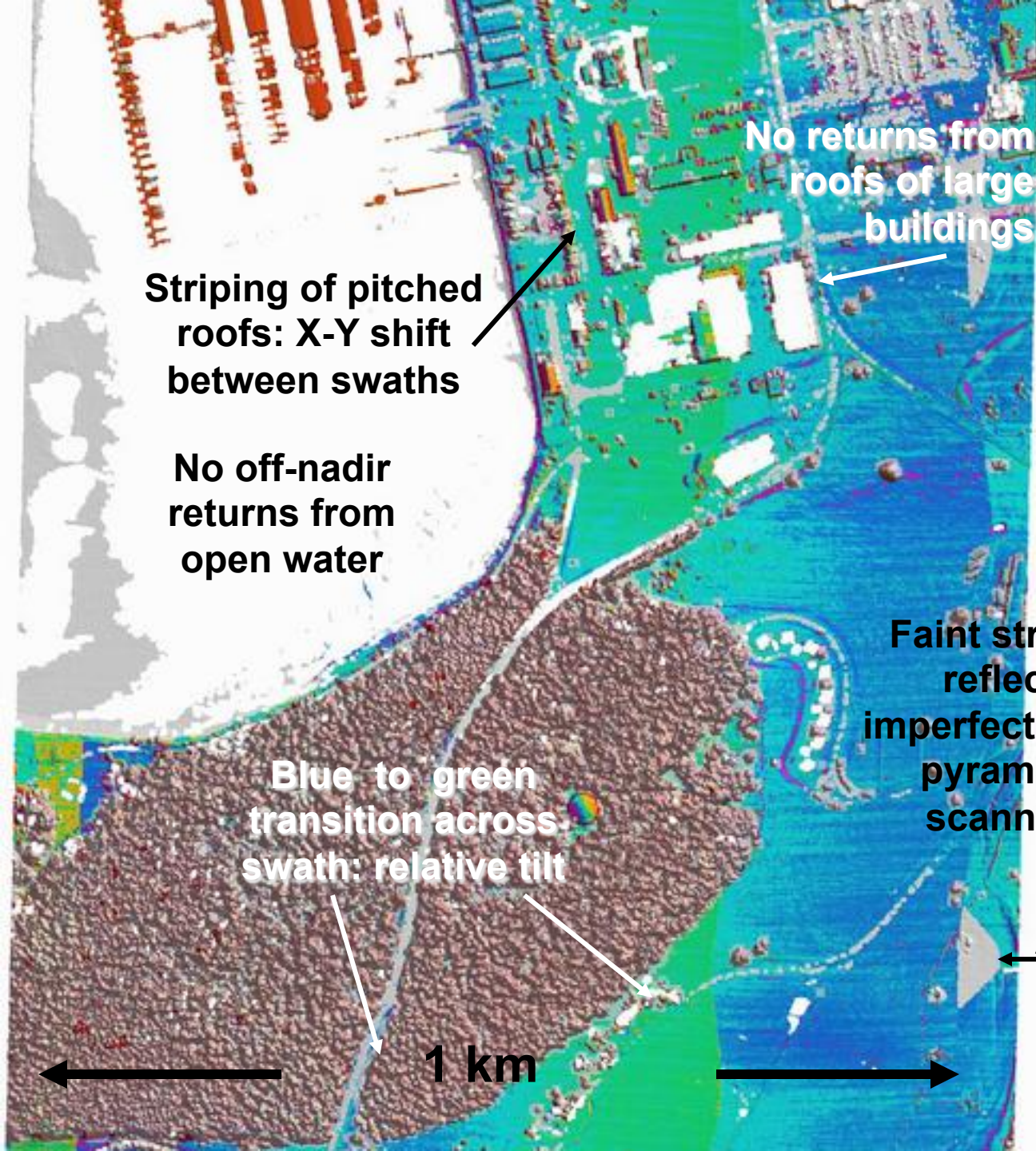
Observation: 3 ft step  
in freeway at tile  
boundary

Inferred cause: tile to  
tile variation in  
inclusion of data,  
“calibration”, and/  
or range-walk  
correction

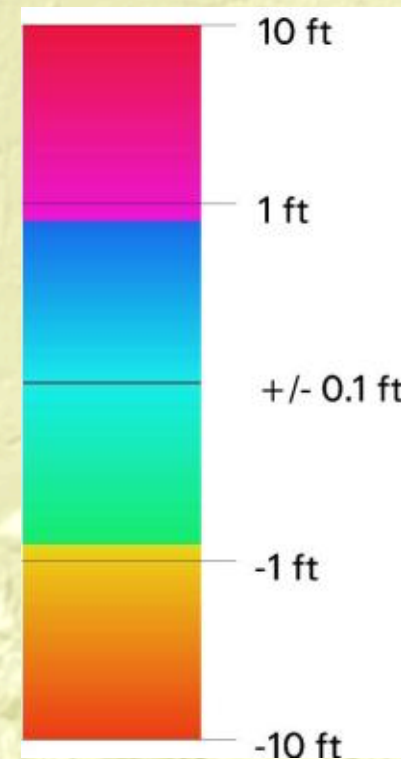
# CONSISTENCY analysis

- Start with tile of multiple-swath data
- Sort on time. Split into swaths at time breaks. For each swath
  - Identify data areas
  - Build surface (1<sup>st</sup>-return points → TIN → lattice)
- Subtract swath surfaces, spatially merge results
- Calculate curvature to identify smooth areas where interpolation is valid
- Make image
  - Saturated color = smooth area with overlap
  - Unsaturated color = rough area with overlap
  - Gray = no overlap
  - White = no returns





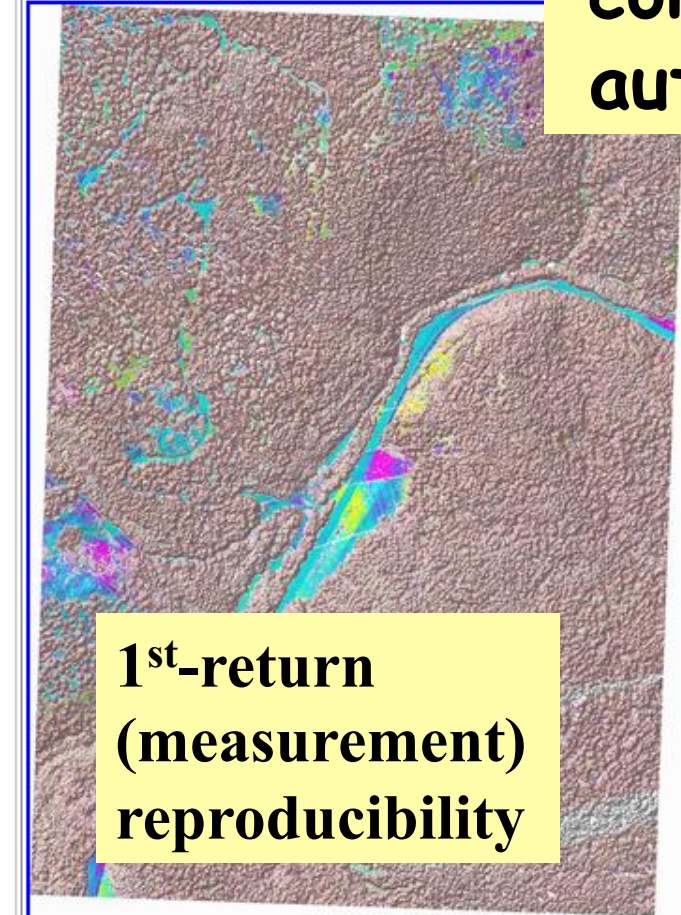
Difference (Z) between overlapping swaths





**q53e4202**  
d:\lidarqa\mwor-2007\consist\_or07fq53e4202.txt  
05 Jan 08 02:12:48 Saturday elapsed time 01:44:01  
16050992 unique returns and 0 duplicate returns

1st-return consistency  
1st-return RMSE, low-curvature areas = 0.38  
95p = 0.783, 98p = 0.989, 99.5p = 1.315

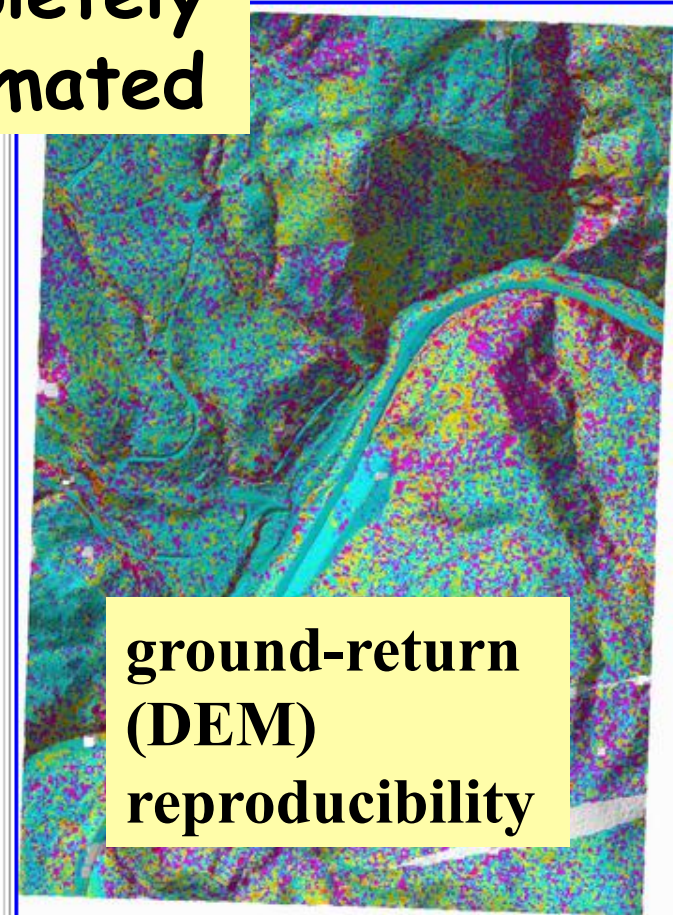


**1<sup>st</sup>-return  
(measurement)  
reproducibility**

[consistency legend](#)

Rectangular area = 1.524 km<sup>2</sup>  
Data area = 1.413 km<sup>2</sup>  
\*percent double coverage = 94.224  
... area = 0.087 km<sup>2</sup>

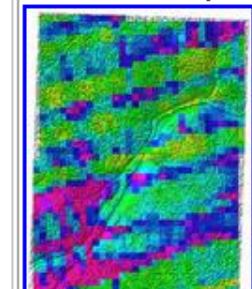
stency  
2.327, 99.5p = 3.832



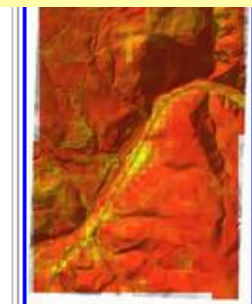
**ground-return  
(DEM)  
reproducibility**

[details](#)  
[return classification](#)  
P1 = 5.0 cm, P2 = 31.5 cm

1st-return density

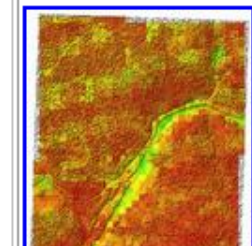


**pulse density**



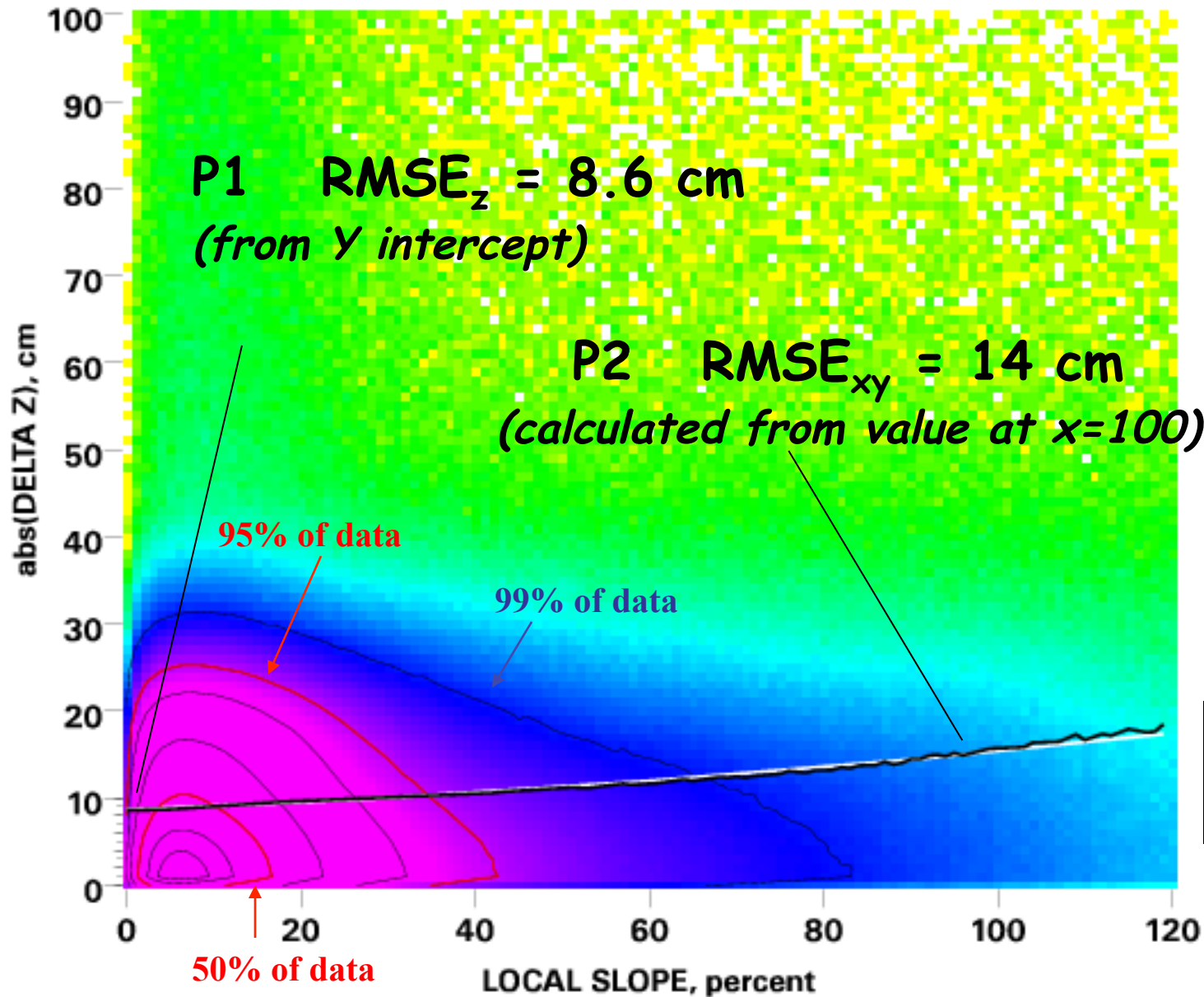
[density legend](#)

ratio ground returns  
to 1st returns





**Z error versus slope**  
**curvature  $\leq 5$**



*$n \approx 25$  million*

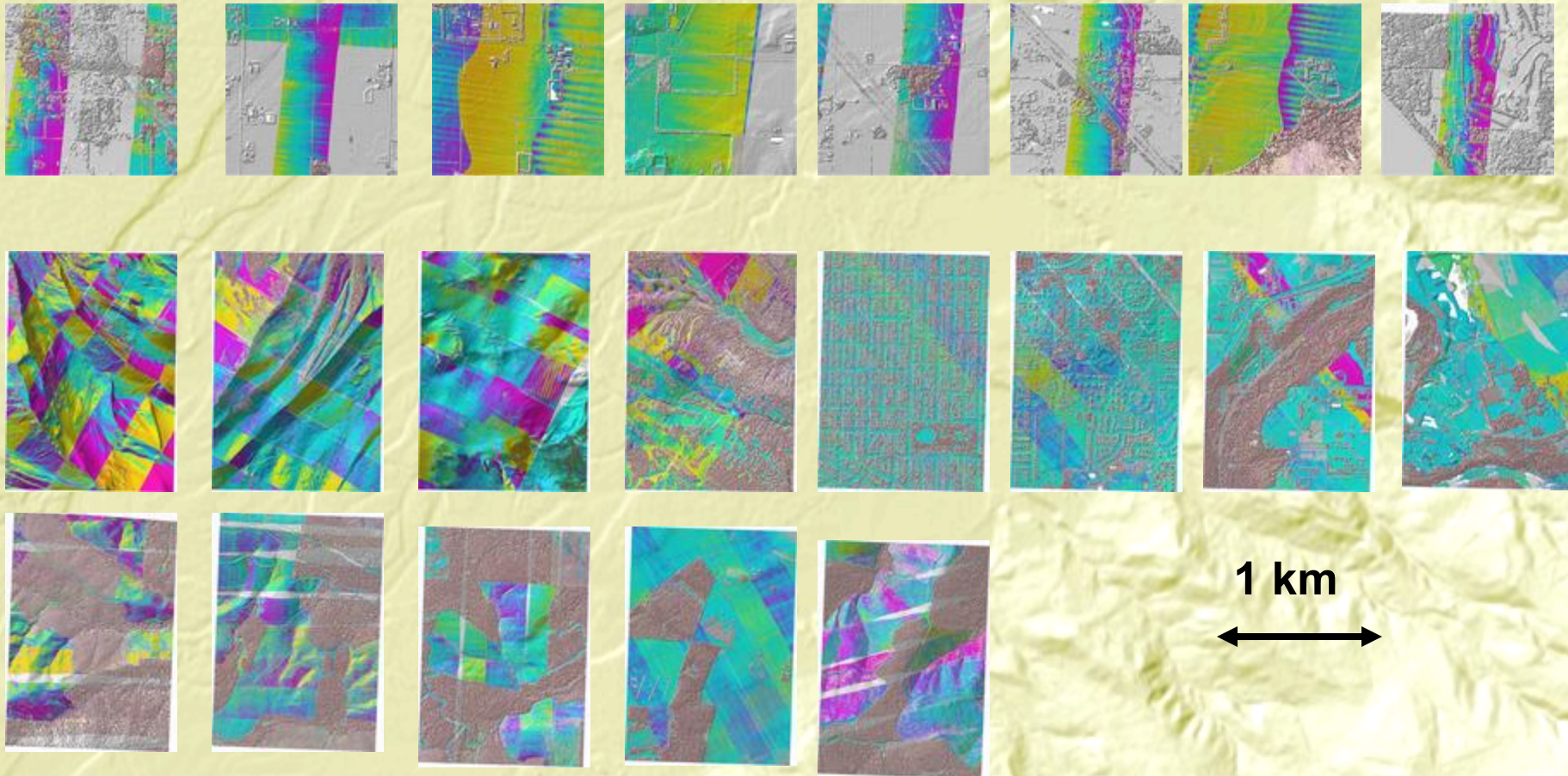
**TerraPoint  
2005 Lower  
Columbia  
survey**

**25% sample of  
two 7.5- minute  
quadrangles,  
2 pulse/m<sup>2</sup>**

**wiggly black line:  
RMS Y for each X**

**white line: least-  
squares best fit  
quadratic**

# Observation: errors in lidar measurements show strong spatial correlation





# Hypothesis: errors in photogrammetric DEMs have little spatial correlation

Why?

- Aerotriangulation and image orientation done with greater care (and more redundancy) than identification of corresponding image points
- Largest source of error has no spatial correlation beyond that imposed by structure of target region

*This relationship between measurement accuracy and intended use is (I hypothesize) empirical and based in experience with photogrammetric DEMs*

maximum allowable rms Z error

20 cm

ASPRS vertical accuracy standard  
National Map Accuracy Standard

2 ft

Minimum Contour Interval



- Uncorrelated errors disappear upon spatial averaging
- Drawing contours (and cut-and-fill calculations) involves spatial averaging
- Contouring minimizes errors in photogrammetric DEMs by averaging them away
- Contouring a lidar DEM, with its highly correlated errors, does NOT minimize errors by averaging



Lidar surveys for contouring (and other averaging operations) should be more accurate than suggested by ASPRS and NMAS standards

Lidar surveys for feature recognition (e.g., finding fault scarps, counting trees) can be significantly less accurate than experience might suggest, provided adequate XY resolution



## Lidar data quality has 3 dimensions

- Usability
- Completeness
- Accuracy

## Evaluate lidar data quality by

- Testing against ground control
- Looking at big images
- Quantifying swath to swath reproducibility and completeness

## Standards for required mean accuracy need revision

- Inundation modeling requires better absolute accuracy than we expect
- Geomorphic mapping (feature recognition) requires less absolute accuracy